## PGSE Series Slim-type Electric Parallel Gripper

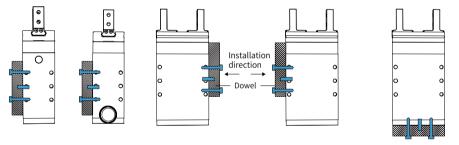
PGSE-15-7

The PGSE Industrial Parallel Gripper is a miniature electric gripper specifically designed to meet the demand for quick grasping in narrow and compact installation spaces in industrial settings.



### Installation

- 1. Front installation: use front screw holes for installation
- 2. Rear installation: use rear screw holes for installation
- 3. Right installation: use right screw holes for installation
- 4. Left installation: use left screw holes for installation
- 5. Bottom installation : use bottom screw holes for installation



### **Product Features**

#### • Ultimate Slimness

The PGSE gripper features a compact and intricate design, with dimensions of only 85.6 x 38 x 23.2 mm (length x width x height), making it extremely slim and compact.

#### High-Speed Response

The PGSE gripper offers rapid opening and closing times, with a minimum response time of as fast as 0.15 seconds for both opening and closing actions. This allows for quick grasping cycles, meeting the high-speed gripping requirements of production lines.

#### • Flexible Installation

DH

ROBO:

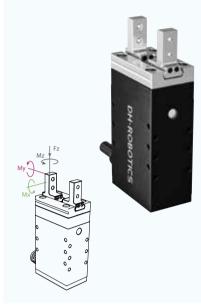
The gripper body of the PGSE model provides multiple mounting options, Coupled with its compact size, it facilitates easy installation in tight spaces.

## Application

The PGSE gripper is suitable for compact production environments, such as the semiconductor and 3C electronics industries, where it can be utilized for gripping, sorting, loading, and unloading of small-sized components.



# **PGSE-15-7**



Static Vertica	Static Vertical Allowable Load			
Fz	70 N			
Allowable Lo	Allowable Loading Moment			
Мх	0.9 N · m			
Му	0.75 N · m			
Mz	0.9 N · m			

 $^* \odot$  . It depends on the shape of the grasping object, the material and friction of the contact surface, and the acceleration of the motion, If you have any questions, please contact us.

 $^{\ast (2)}$  Use optional communication, need external communication conversion box, please consult the sales staff for details

#### **Technical Drawings**

Secure as least100mm Cable allowable bending radius R50mm

8

23.20

23,40

#### Parameters

Product Parameter				
Gripping force (per jaw)		6~15 N		
Stroke		7 mm		
Recommended workpiece weight $^{\star \scriptscriptstyle \mathbb{D}}$		0.25 kg		
Opening/closing time		0.15 s/0.15 s		
Noise emission		< 60 dB		
Weight		0.15 kg		
Driving method	Precise planetary gears + Rack and pinion			
Size 85.6 mm x 38 mm x 23.2 mm				

Working Environment					
Communication interface	Modbus RTU (RS485)、Digital I/O <sup>*<math>_{\odot}</math></sup>				
Rated voltage	24 V DC $\pm$ 10%				
Rated current	0.15 A				
Peak current	0.8 A				
IP class	IP 40				
Recommended enviro	onment 0~40°C, under 85% RH				
Certification	CE, FCC, RoHS				

•		0	0	0	0
Build-in	Gripping Force	Position	Speed	Drop	Self-locking
Controller	Adjustable	Adjustable	Adjustable	Detection	Mechanism

