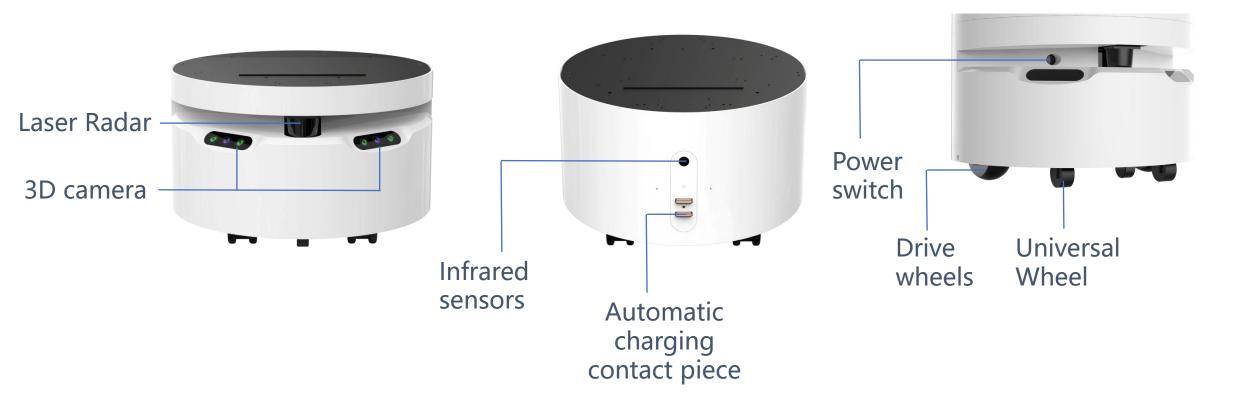


# ATEAGO S5 Robot chassis





## Overview of product mix





## Why choose a robot chassis?

1. High R&D investment costs

Pain points faced by robotics companies

2. Fast product iteration



3. Long payback period



## **Product Description**



#### **ATEAGO S5 Robot chassis**

The chassis is built with ATEAGO's navigation and positioning system, using 270° LIDAR and double 3D cameras. The driving wheels are designed with an independent suspension structure, significantly enhancing the smoothness of the robot's movement, while the SDK platform is open to all developers, providing a full set of development documentation to help developers quickly validate and develop robot applications.



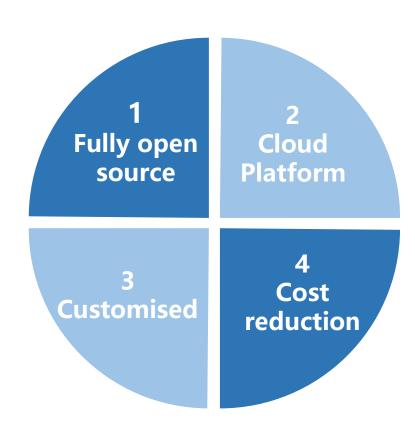
## **Product Advantages**

#### **Open SDK platform**

Completely open hardware and software platform, providing API interface, rich technical support documentation, assisting product development throughout.

#### **Customised development**

Extremely scalable, allowing users to customise the upper layer of the application architecture according to their actual needs



#### **Cloud Service Platform**

Support remote navigation to build a map for deployment, real-time display of the robot chassis operating status, saving time and easy to operate

# Reduced development costs

The chassis has a mature and stable navigation solution, helping companies to shorten product development cycles and reduce R&D investment costs



## **Functional features**



#### **01 Super capacity**

The S5 chassis is made of sheet metal construction, with a large capacity of 60 kg, stable and undeformed

## **02 Intelligent obstacle avoidance**

270° autonomous obstacle avoidance, flexible steering, stable and safe operation

# 03 Remote navigation deployment

Support for remote navigation to build maps, easy and fast robot installation and deployment

# 04 Independent suspension structure

Smoother robot movements, smooth steering and less wobbling

# **05 Autonomous dispatch** system

Multi-machine collaboration allows for dynamic adjustment of robot avoidance according to task priority, enabling efficient and stable delivery

#### **06 Automatic recharging**

Automatic return to charging when the power level falls below the minimum, no manual operation required



### **Open SDK platform**

#### **Extensive interfaces and scalability**

The SDK is open to all users, providing a rich API interface with great scalability, and for customers with certain development capabilities, customised development can be achieved according to the needs of scenario applications, meeting the diverse needs of the market for mobile robot chassis.

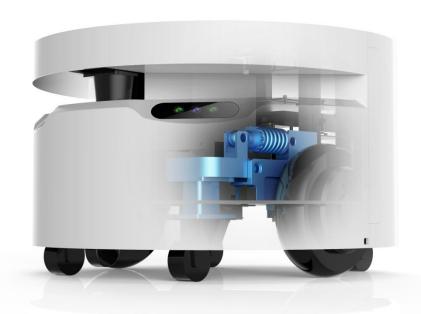




### Independent suspension structure

#### Both side drive wheels with shock absorbing suspension system

During the movement of the robot, the posture is smoother, the steering action is small, and there is no tipping, effectively reducing problems such as slipping of items during delivery.







#### Autonomous obstacle avoidance

Equipped with ATEAGO SLAM synchronous positioning map building system, high-precision navigation and positioning, Laser radar, dual 3D cameras, all-round perception of the surrounding environment, efficient and stable operation.

#### **Single line Laser**

Detection distance 25m, laser wavelength 905 nm Working area 270°

#### **Dual 3D cameras**

Vertical angle: 63° Horizontal angle 79°



# No need to paste code, accurate positioning

#### Deployment without posting code

- Robotic navigation deployment without the need to affix codes for auxiliary positioning.
- no need to affix codes to the ceiling and no aesthetic impact on the decoration.
- Customised planning of delivery routes for easier operation.

#### Highly accurate navigation and positioning

- Proven and stable navigation algorithms for precise positioning
- Multi-sensor fusion technology with LIDAR + dual 3D cameras for real-time sensing of the surroundings





## Autonomous dispatch system

# Multi-machine collaboration and orderly operation Avoid blocking the "machine"

The built-in scheduling system, with multimachine collaboration, can dynamically adjust robot avoidance according to task priority to achieve efficient and safe, stable and reliable delivery efficiency.





## **Autonomous lift rides (Optional)**





## Lithium iron phosphate batteries



High temperature resistant, non-combustible and safe enough



Fast charging support for faster charging



Long battery life, discharge cycles Up to 2000 cycles



Green, energy efficient and environmentally friendly

# No fire, no combustion, absolutely safe, longer battery life



Lithium iron phosphate batteries

(25.6V/25Ah)



## **Automatic recharging**

Custom set minimum power value, when the robot's power falls below the minimum value, it automatically returns to charging without manual operation.









## Wide range of applications

The products are widely used in robotics companies, research institutes, universities and robotics training institutions.











## **Product parameters**

Product number: ATEAGO S5	Life time: 20 hours
Cruising speed: 0.1~1m/s	Charging time: 4 -8hours
Battery capacity: 25.6V/25A·H	Operate System: Android 5.1 or above
Network: Wifi	Product weight: 34KG
Machine size: 500(L)*500(W)*310(H)MM	Bearing weight: 60KG





# Thanks for watching

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