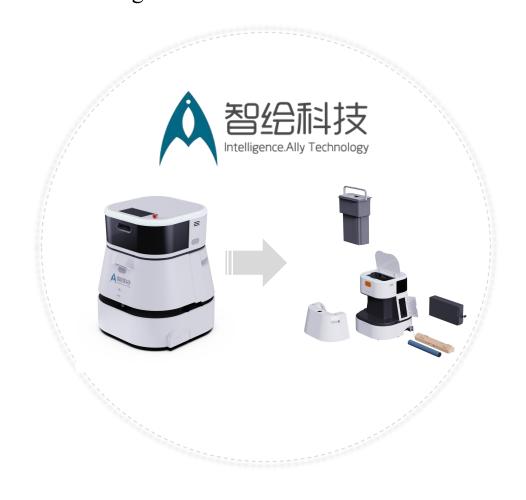




Product Introduction

The cleaning robot integrates scrubbing, vacuuming and mopping functions. It enables self-recharging and self-cleaning, and has been widely employed in hospitals, shopping malls, schools, exhibition halls, office buildings, terminal buildings and other scenarios.





Intelligent Navigation

Intelligent navigation with obstacle avoidance, smart planning for cleaning routes, real-time detection of pedestrians and surrounding obstacles, and flexible execution of cleaning tasks.



Simplified Operation

User-friendly design allows a new cleaning task to begin within three clicks (scheduled tasks require no extra operation).



Modular Quick-Detach Design

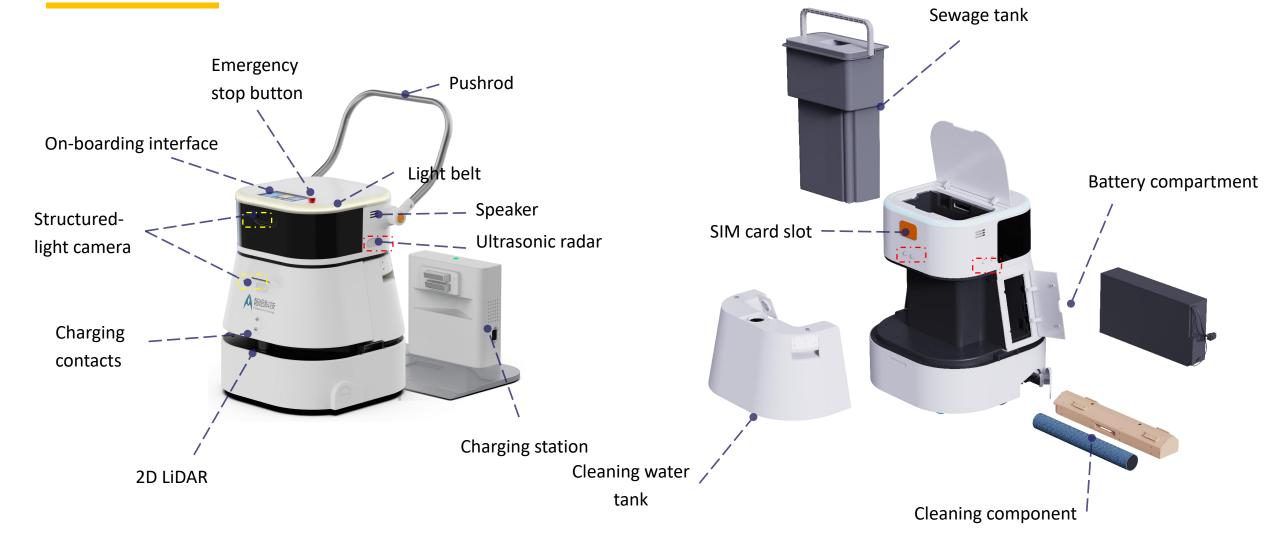
Modular design makes regular maintenance, component repair, and consumable replacement easier.



Multi-Mode Interaction

Multiple interaction methods including onboard interface, mobile App and romote control enable quick and flexible use. For example, deploying cleaning task on onborad interface by one click, real-time notification of robot status on mobile App.

Component Description



Functions







Scubbing

- Suitable for : dry or wet floor with garbage
- Working hours: up to **5** hours when fully-charged

Mopping

- Suitable for: floor with dry garbage or less water; daily maintenance
- Working hours: up to **12** hour when fully-charged

Vacuuming

- Suitable for: dry floor, carpet,garbage smaller than the suction port
- Working hours: up to **4** hours when fully-charged

Floor types



Scenarios













Office

Hotel

Exhibition hall

Terminal Building

Real estate

Hospital













Factory

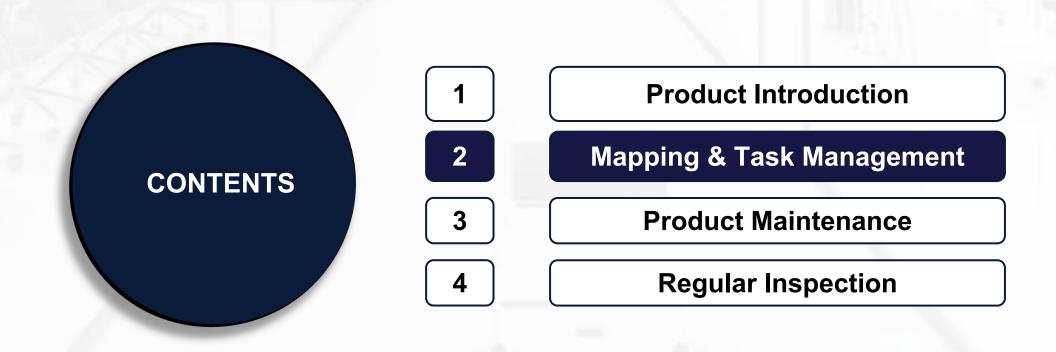
Supermarket

Subway station

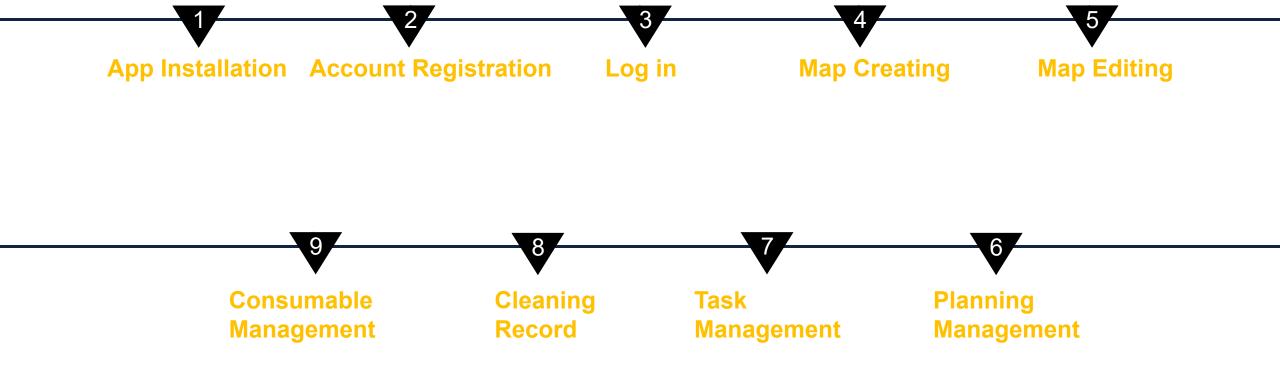
Hospital

Restaurant

Shopping center



9 Steps to Manage



App Intallation

You can download and install the **AllyBot** mobile app from the Android App Market or by scan the QR code. The launch icon is shown below.



Search for 'allybot' in the App Market



Download App

- Currently the IOS App has only Chinese language package, and the multi-language package will be lauched soon.
- The software is continually updated with rapid iterations. You can contact our technical support team to obtain the latest AllyBot software packag
 for installation and use.
- Please ensure that your robot and smart phone are connecting with the same WiF

Web-based operation



- Power on the robot
- Search the WiFi list for the robot WLan with the name of its SN code (eg: SN0001→0001)
- Connect the WLan with password (initial password: Zhkj2015)
- Open a browser and enter the IP address: 192.168.8.188:32769 to access the webpage

Registration & Log in

Click Register Click the "Register"
button at the top right
of the login page to
register a new
account

Enter Information

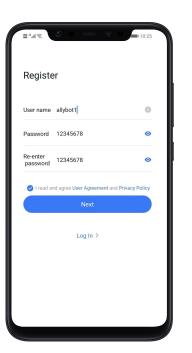
Enter a valid username, password, and confirm the password

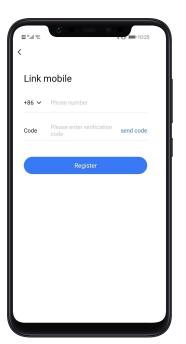
Link Mobile Link your account with mobile number by enter verification code.



Note:

Please provide your registered "username" and "phone number" to our technical support team. We will upgrade your account to an administrator account.





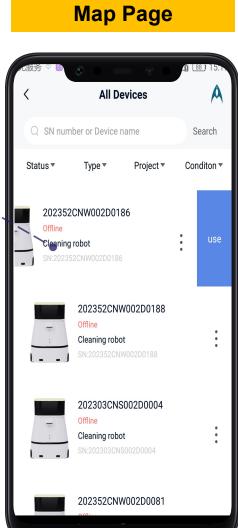
Log in

- Password login
- SMS login

Map Creating

Swiping left reveals a click Maps to manage "use" button, then click

"use" to connect.



New Map

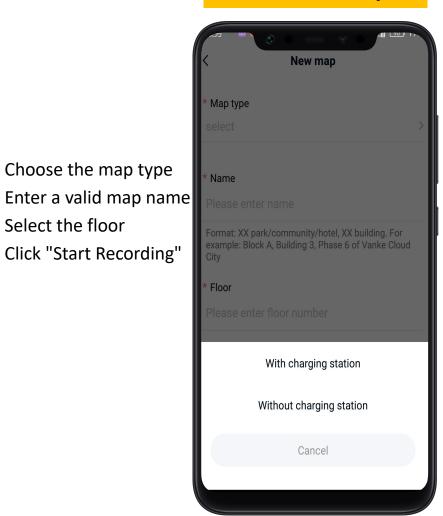


Map Creating

Choose the map type

Select the floor

Name the map



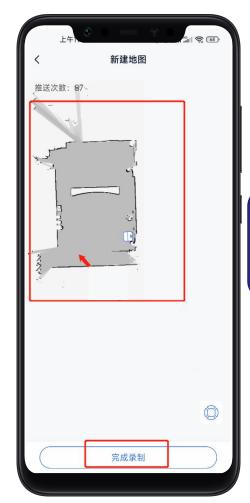




Remote control mode:

- 1. Press remote switch
- 2. Press key "5" for linkage
- 3. Wait the light belt to turn blue

Map Recording



- 1. Place the robot about 50cm in front of the charging station
- 2. Control the robot to scan the surroundings

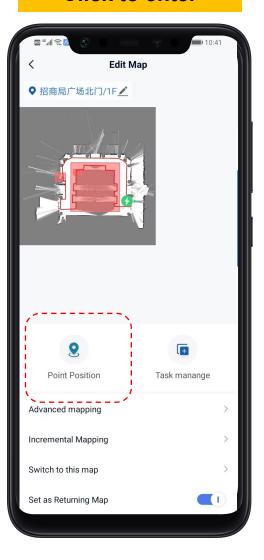
Note:

Please control the robot the move as near the wall as possible to ensure a higher pricision and avoid any ghost.

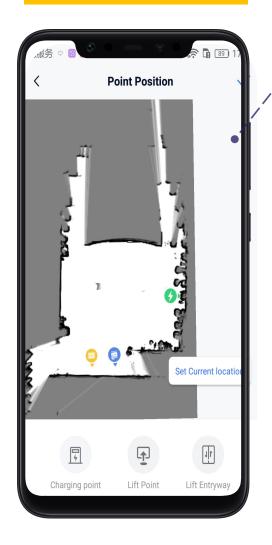
- 3. Return the robot near the starting point to form a closed loop
- 4. Click "Finish Recording" to save the map

Map Editing- Point Marking

Click to enter



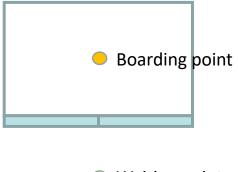
Point Marking



Set special points on the map:

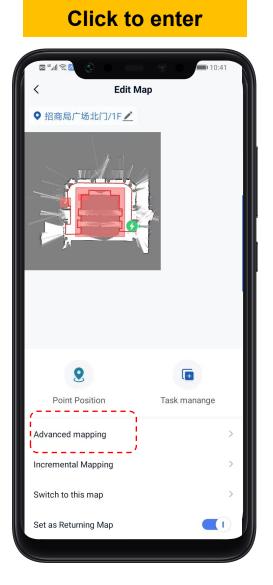
- Charging point for without-station map
- Waiting Point
- Boarding Point (if cross-floor cleaning task)



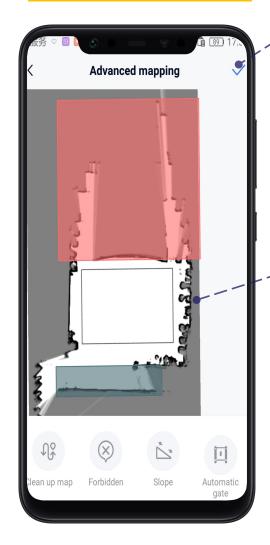


Waiting point

Map Editing-Fine Marking







Click "\" to save all editions

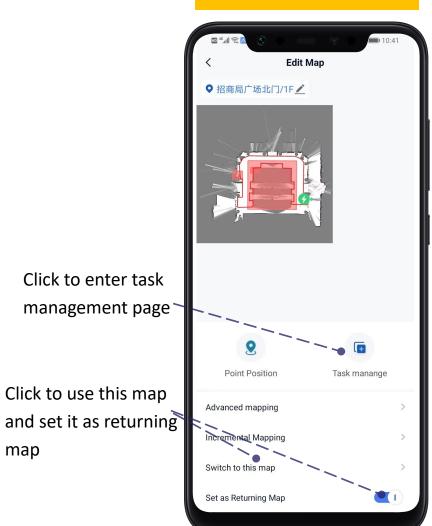
Mark special areas on the map:

- Accessable areas
 filtering out noises caused by temporary
 obstacles
 - No-go zones
- Slope areas
 the robot's movement slows down in slope areas

Priority: restricted area > slope area > accessible area

Map Editing-Planning Management

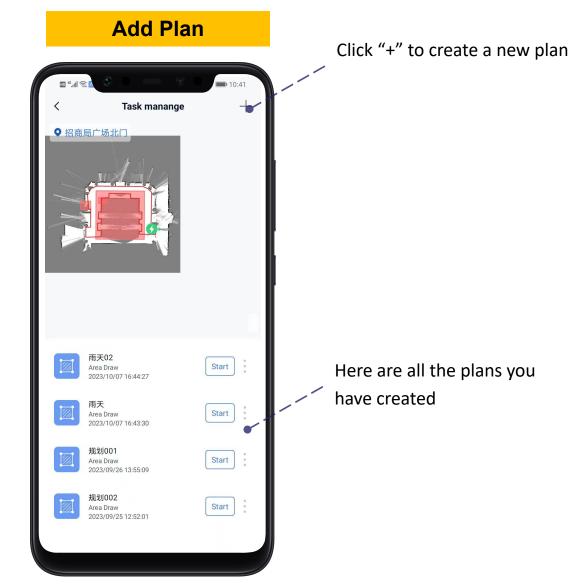
Click to enter



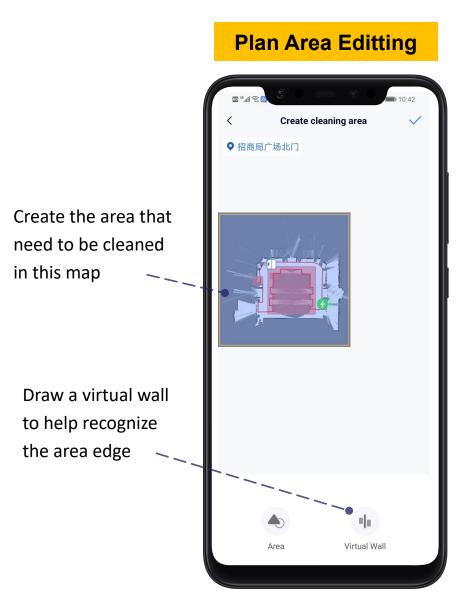
Click to enter task

Click to use this map

map

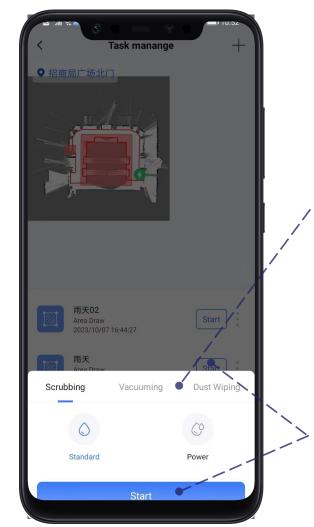


Map Editing-Planning Management





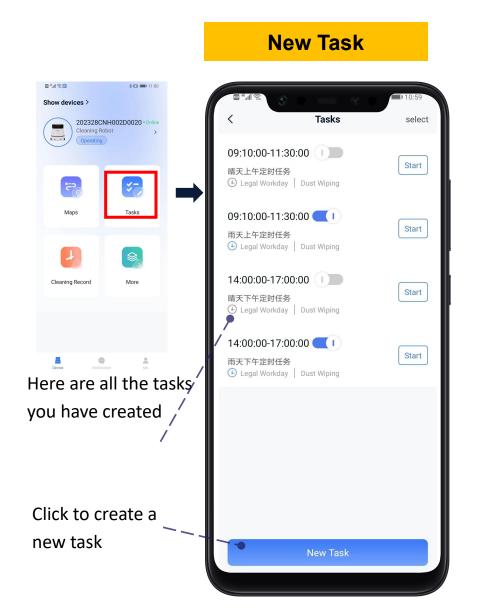
Working Mode Selection



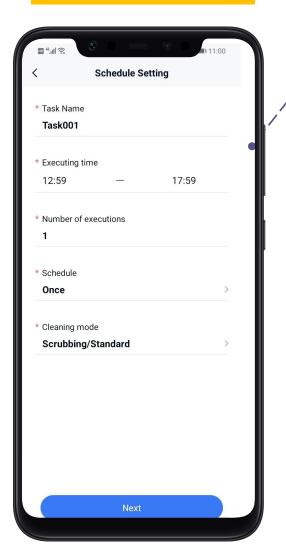
Select cleaning modes and intensities here

Click "Start" to start cleaning immediately, or ignore it.

Task Management



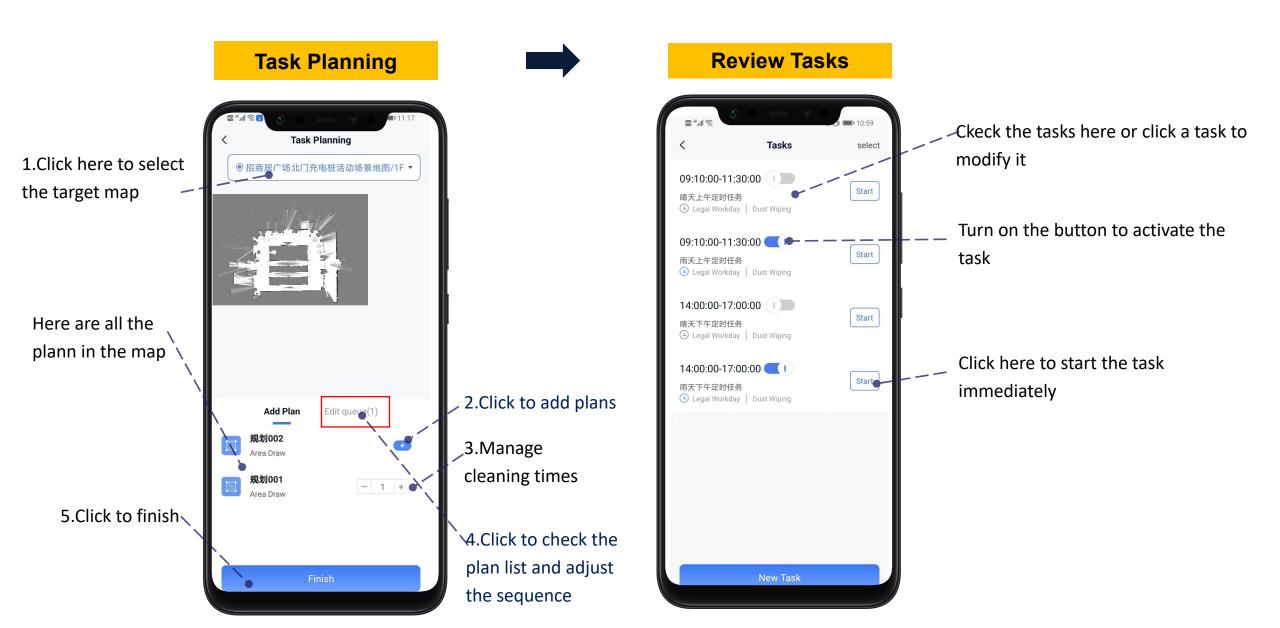
Schedule Setting



Set general information for the new task:

- Name
- Time
- Number
- Schedule
- Cleaning mode

Task Management



Cleaning Record

Click to enter

Click to check 7-day Records cleaning record 7-day data all 2 Click check details of a 2024/08/14 16:48-18:18 Canceled single cleaning task ● abil | Scrubbing **≱**:©: ■ 11:00 2024/08/14 15:28-15:31 Canceled 临时 | Scrubbing 202328CNH002D0020 * Online Cleaning Robot 2024/08/13 11:00-11:04 Finished 墙边 | Scrubbing 2024/08/12 16:18-16:21 Canceled Task001 | Scrubbing Cleaning Record 2024/08/12 16:02-16:05 Canceled 演示洗地 | Scrubbing 2024/08/12 15:02-15:22 Finished



Cleaning Data

Task Name

Number of

executions

Operator

Cleaning

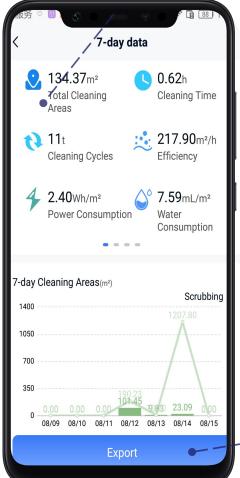
Cumulative

Mode

Cleaning time

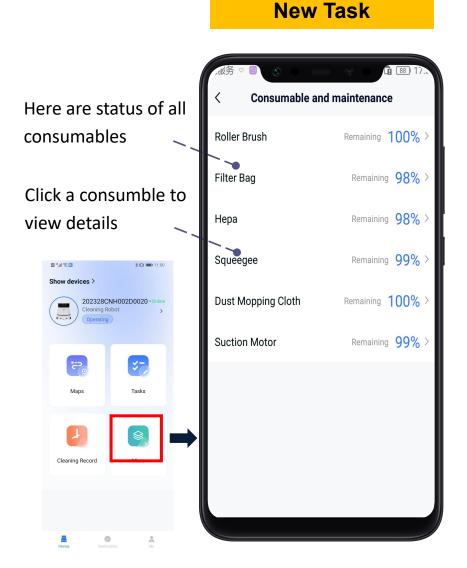
View Record



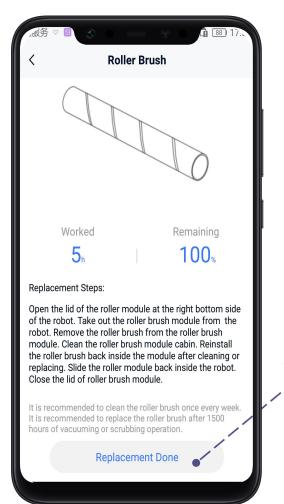


Click to export cleaning record

Consumable Management



Schedule Setting



Click 'Replacement Done to reset _ data after replacing the consumable'



Maintenance Overview



Adding water

- 1 Press the latch on the base of the cleaning water tank to unlock it.
- 2 Push the handles on both sides of the water tank upward to unlock the left and right locks, and then pull the water tank outward horizontally.
- ③ Open the silicone cover of water tank and fill it with tap water.

Disassembly of cleaning water tank



Sewage discharge

- ① Lift the top cover of the robot and take out the sewage water tank.
- ② Remove the sewage tank cover and empty the sewage from the tank.



Sewage tank cleaning / 7 days

- 1 Take out the sewage tank and clean the interior with a brush
- ② Replace the filter bag/ dust bag

Sewage tank cleaning

Use a brush to clean the interior



Before

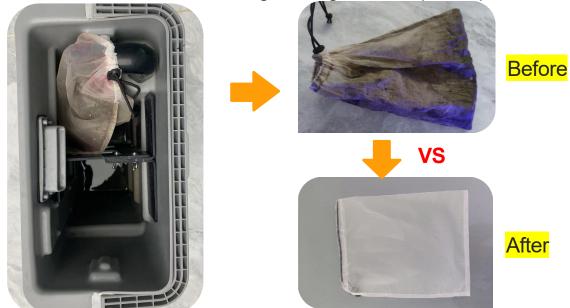
VS



After

Filter/ dust bag cleaning

- Loosen the pull rope of the filter/dust bag below the dirt suction pipe of the sewage tank, and remove it.
- Clean the bag with water and let it air dry, or replace it directly. Reinstall the clean filter bag and tighten the pull rope.



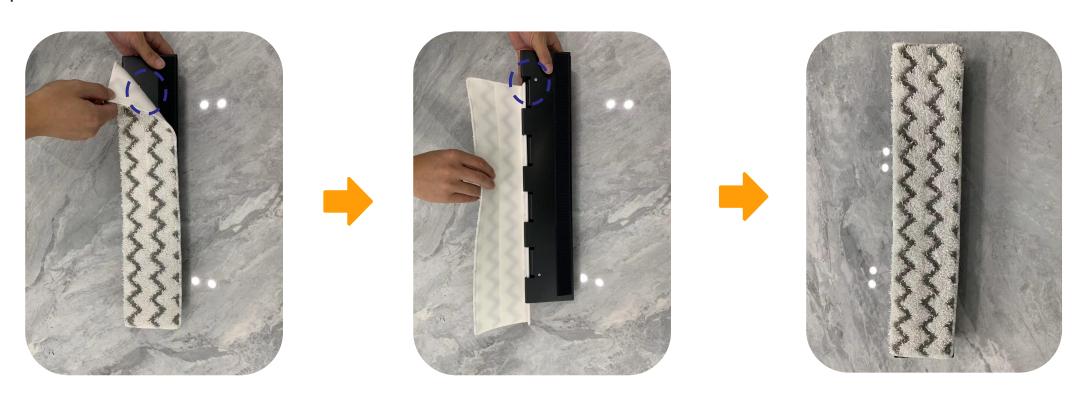
Scrubbing/ Vacuuming roller brush replacement / 7 days

- ① Loosen the screw on the limit bar of the right compartment cover and pull up the limit bar.
- 2 Pull the brush out of the component.
- ③ Clean the brush and component and remove any debris, or directly replace the brush with a new one.
- ④ Reinstall the brush into the scrubbing/vacuuming compartment, pull back the limit bar and tighten it with the screw. Note: the without-spline-shaft side of roller brush need to be aligned with the bearing cover

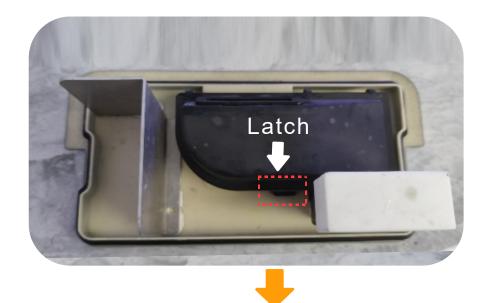




- ① Gently remove the mopping cloth from the velcro, and pull out the mopping cloth limit column from the mopping plate O-ring.
- 2 Shake off any debris on the mopping cloth, clean it, and let it air dry.
- ③ Insert the limit column into the O-ring, and stick the cleaned or new mopping cloth flatly onto the mopping plate.



HEPA replacement / 15 days





HEPA replacement

① Flip over the removed sewage tank cover, release the latch of the HEPA flip cover, and remove the flip cover.

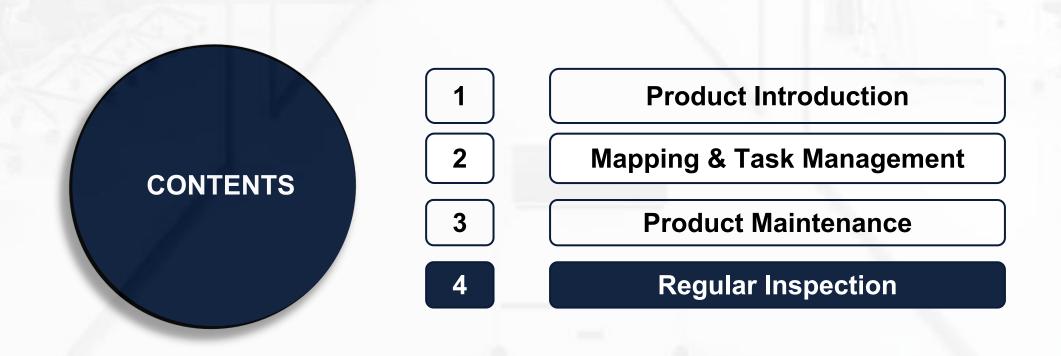
- ② Take out the HEPA, clean it with water, and let it air dry or replace it directly.
- ③ Reinstall the cleanHEPA and fasten the flip cover







New HEPA



Inspection Overview



Cleaning Component

- Roller brush
- Suction port
- Rubber strip

Water Tanks

- Cleaning water tank
- Sewage tank

Sensors

- Structured-light camera
- 2D LiDAR
- Water flow sensor

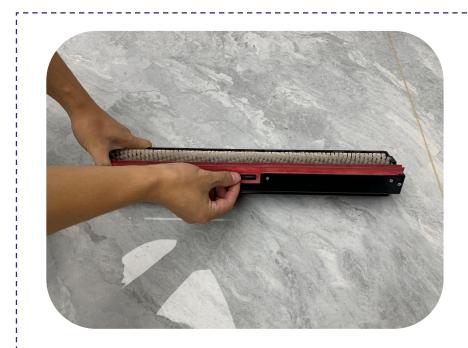
Wheels

- Motor drive wheel
- Universal wheel

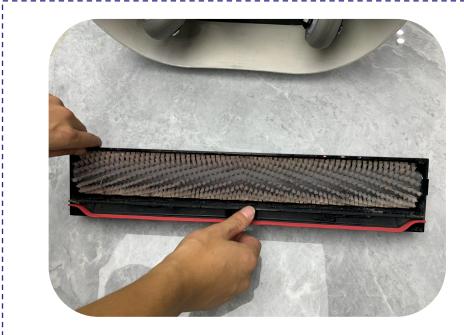
Cleaning Component / 7days

Pull out the cleaning component from the cleaning compartment;

- ① Check for foreign objects entangling the roller brush.
- ② Check for blockages in the dirt suction port/ on the rubber strip.
- ③ Check for wear and tear on the roller brush and rubber strip.



Remove blockages in the dirt suction port



Replace the worne rubber strip

Robot Sensors Cleaning / 30 days









Sensor cleaning

Use a soft cloth to wipe off the dust on the surface of structured light cameras and 2D LiDAR.

Water Tank / 15 days

- ①Check for wear and surface dirt of the pin/copper column of the clean water tank.
- ②Check for wear and surface dirt of the pin/copper column of the sewage tank.

Cleaning water tank



Sewage tank



Water Tank / 30 days

- ① Remove the silicone cap to inspect the filter pipe for foreign objects, and clean it with tools.
- ② Remove the sewage tank, check for foreign objects in the suction port, and clean it with tools.

filter pipe

suction port





Wheels / 30 days

- ① Power off the robot, and remove the cleaning water tank and sawege tank
- 2 Gently lay the robot down and clean foreign objects entangling the wheels
- ③Reinstall the tanks and power on the robot

Universal wheel cleaning



Motor drive wheel cleaning

