

| | ATEAGO L1 Automatic | Unmanned Forklift Pallet Mover Pallet Stacker |
|-----------------------|--|--|
| Photo | | MASK NIL (III-2) |
| | Rated load(Q) | 2000kg |
| | Vehicle weight (including battery) | 370kg |
| Basic Specs | | 1645mm |
| | Overall vehicle width (including safety edge) (b1) | 850mm |
| | Navigator bracket reference height (h2) | 1890mm |
| | Load center distance(c) | 600mm |
| | · / | 865mm |
| | Wheelbase(y) | 1150mm |
| | Fork dimensions(I/e/s) | 1150/170/60mm 680mm is standard, can be customized in various sizes such as 680, 600, |
| | Fork outer distance(b6) | 540, etc. |
| Fork | Lift height(h3) | 205mm |
| | Minimum ground clearance of the fork surface(h6) | 85mm |
| | Minimum ground clearance (when fork is raised)(m1 | 40mm |
| | Right-angle stacking aisle width (for 1000×1200 pallet) 1200 across fork direction C500(Ast) | 1975+200mm(safety distance) |
| Moving performance | Right-angle stacking aisle width (for 1000×1200 pallet) 1200 along fork direction C600 (Ast) | 1960+200mm(safety distance) |
| | Turning radius (including safety edge)(Wa) | 1360mm |
| | Travel speed, fully loaded/empty | 1.0/1.5 m/s |
| | Lift speed, fully loaded/empty | 40/50 mm/s |
| | Descent speed, fully loaded/empty | 50/40 mm/s |
| | Maximum climbing ability, fully loaded/empty(S2-5n | 3%/5% |
| | Navigation | Free/Track/Hybrid/Follow-me |
| | Whether to support outdoor operation | Supports use within qualified campuses |
| | Positioning accuracy | ±5(mm)/±1(°) |
| | _ | Electromagnetic |
| | Tire type, drive side/load side Tire size, load side | Polyurethane |
| | Tire size, load side Tire size, drive side | φ80*70mm φ210*75mm |
| Tire | Balance wheel | φ72*23mm |
| Tire | Number of wheels, front/rear (x=drive wheels) | 1x+4/4 |
| | Wheel base, drive side(b3) | 470 |
| | Wheel base,load side(b3) | 520 |
| | Drive motor power (servo motor) | 1 kw |
| Drive | Lifting motor power, (S3-10%) (DC compound | 0.8 kw |
| | excitation) | U.O NW |
| | Steering system | Electric steering (servo) |
| Usage environment | Steering motor (servo motor) | 0.4 kw |
| | Waterproof and dustproof level | Whole vehicle IP43 |
| | Working temperature | -10°C~65°C; Anti UV; Anti-corrosion |
| | Storage temperature | -20°C ~65°C 5~40°C (Indoor) |
| | Charging temperature | 5 40 C (IIId001 <i>)</i> |
| Display & Touch | 10.1-inch screen, resolution 1280*800 | |



| | 4G | Support,FDD B1/B3/B5/B8,TDD B38/39/30/41 |
|----------------------------|---|---|
| Network communication | 5G | Supported, 5G module needs to be customized and installed |
| | Data quota | 2G/month per robot |
| | WIFI | Wifi module (AP6256) 2.4G&5GHz, supports 802.11a/b/g/n/ac protocol |
| | Bluetooth | Bluetooth 5.0, BLE |
| os | Android 11+ Linux(Ubuntu) | |
| Sensor | Navigation lidar*1 | Detection range: 360°, detection distance: 0.05 ~ 40m |
| | Obstacle avoidance lidar*2 | Detection range: 200°, detection distance: 0.05 ~ 40m |
| | Fork tip obstacle avoidance lidar*1 | Detection range: 180°, detection distance: 0.05 ~ 12m |
| | Depth camera*2 | FOV: H 72°(±3°) V 50.5°(±3°), detection distance: 0.3 ~ 4m |
| | RGB camera*2 | 215°FOV, resolution 1280*720 |
| | Wheel speedometer | 6DOF; rate dynamic range: ±2000dps; accuracy: 0.01 degrees odometer |
| | Whiteel Speedoffieler | Charging voltage: 48V |
| | Battery | Capacity: 50Ah |
| | | Battery life: 6-8 hours |
| | | Deploying charging piles can achieve 7*24h service |
| | | Charging method: automatic/manual |
| | | Battery weight: 55kg |
| Charging & battery life | | 0%-100% charging time: 1.6 hours |
| , | Charging Pile | For details about charging piles, please see the "Charging Piles" table |
| | | H*W*D: 370mm*292mm*395mm |
| | | Weight: 30kg |
| | | Input: 100-240V ac~50/60 Hz |
| | | Output: 32~64V dc==1-30A |
| | | ARM® Quad-core Cortex-A76 2.4Ghz + ARM® Quad-core Cortex-A55 |
| | Chassis CPU | 1.8Ghz |
| | Screen CPU | ARM® Quad-core Cortex-A55 2.0Ghz |
| | Chassis GPU | Mali-G610 |
| | Screen GPU | Mail-G52 |
| Control | Chassis memory | RAM: 8GB dual-channel LPDDR4; ROM: 64GB high-speed eMMC |
| | Screen memory | RAM: 2GB dual-channel LPDDR4; ROM: 16GB high-speed eMMC |
| | Image process | Support OpenGL ES 1.1/2.0/3.0, OpenCL1.2, Directx11 |
| | | Embedded high-performance 3D acceleration hardware |
| | | H.264/H.265/VP9 up to4Kx2K@60fps H.264/H.265 decoder supports 10bit decoding |
| | | 1080P multi-format video decoding, supporting H.264, VP8 and MVC |
| | Indicator light | LED |
| Interaction | Loudspeaker | 2 |
| | Emergency stop button | 2 |
| Safety | Bumper | Front |
| External device | External device | Elevator control, automatic doors control, notification lights and speakers, pagers, Pads, following bracelets, rollers, shelves, pallets |
| Platform | WeChat、APP | WeChat remote management, the mini program can realize functions such as issuing robot task instructions, editing map functions, and visualizing task statistics, without downloading and installation. |
| | Robot management big data cloud platform | Permission allocation and business management of robot users; operational data analysis |
| | Remote monitoring platform | Real-time status monitoring of robots; real-time alarm and remote processing of faults; |
| | Remote deployment management platform | Remote deployment can be realized, and the robot remotely scans and edits the map. |
| | Remote dispatch management platform | Remote cross-space scheduling |
| | Real-time data visualization large screen | Display the real-time status and operational statistical analysis of robots under different businesses |



| ATEAGO 48V30A Intelligent Forklift Charger | | | | |
|--|---|--|--|--|
| Photo | | | | |
| Electrical Parameters | | | | |
| Input Voltage | Single 220Vac, ±20% | | | |
| Input Voltage Frequency | 50/60Hz, ±5Hz | | | |
| Charging Voltage | 32~64Vdc 1~30A | | | |
| Charging Current Charging Power | 1.5kW | | | |
| Efficiency | 3.3KVV ≥92%@220Vac50-100%Load (Max. over 93%) | | | |
| Power Factor | ≥0.95@220Vac50-100%Load | | | |
| Harmonic Current THD | ≤ 5% | | | |
| Voltage Regulation Accuracy | ≤±1% | | | |
| Current Regulation Accuracy | ≤±1% | | | |
| Input/Output Interfaces | 16.4 National Standard AC power and 2 maters (including internal uniting length) | | | |
| Input Power Cord Automatic Charging Interface | 16A National Standard AC power cord, 3 meters (including internal wiring length) 100A copper-made two-pole brush block | | | |
| Manual Charging Interface | 50A Anderson connector, gray, 3 meters (including internal wiring length) | | | |
| Communication Ports | | | | |
| BMS Communication | None | | | |
| Descripted Desire | CAN Bus (can communicate with battery) | | | |
| Reserved Ports | RS485 port (optional Wi-Fi module) Ethernet port (for backend system integration) | | | |
| Human-Machine Interface | Ethernet port (for backend system integration) | | | |
| Touch Screen | 4.3 inches | | | |
| Indicator Lights | Green: Standby/Full | | | |
| | Yellow: Charging | | | |
| 14 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 | Red: Fault | | | |
| Mechanical Parameters | Floor mounted | | | |
| Installation Dimensions (H*W*D) | Floor-mounted 370mm*292mm*395mm | | | |
| Brush Block Stroke | No extension (customizable) | | | |
| Brush Block Ground | , , | | | |
| Clearance | 130mm height, adjustable ±30mm via foot cups | | | |
| Protection Level | P20 | | | |
| Cooling Method | Forced air cooling | | | |
| Environmental Parameters Operating Temperature | '-20°C ~ 45°C | | | |
| Storage Temperature | '-40°C ~ 70°C | | | |
| Operating Humidity | 0 ~ 95%, non-condensing | | | |
| Altitude | ≤2000m | | | |
| Protection Features | | | | |
| Emergency Stop Button Leakage Protection | Press to stop charging, rotate to reset AC-type leakage protection | | | |
| Communication Interrupt | | | | |
| Protection | When CAN communication charging is set, charging stops after 5s if communication is interrupted or times out | | | |
| General Protections | Input over/under voltage protection, output over-voltage protection, output over-current protection, short-circuit protection, grounding protection, over-temperature protection, brush block motor stall protection, battery anti-reverse protection | | | |
| Charger Dimensions | <u> </u> | | | |
| Charger Difficultions | | | | |
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