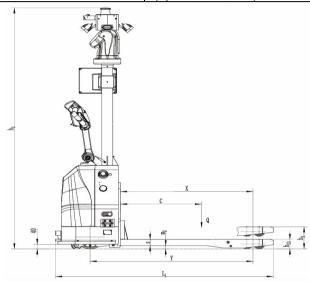
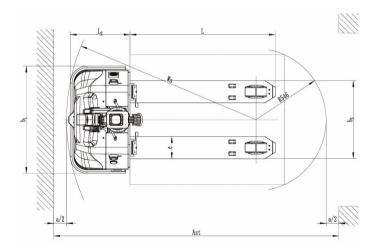
ATEAGO POPOTIVE	l 1 Solf-Drivi	ng Autonomous Forklift
ATEAGO ROBOTIKS		
Vehicle weight (including battery) Vehicle length (including safety edge) Vehicle width (including safety edge)	kg L1 (mm) b1 (mm) h1 (mm) C (mm) X (mm)	1500 350 1610 824 2120 600 980 1210
Fork size Fork outer distance Lifting height Minimum height of fork surface from ground	l/e/s (mm) b5 (mm) h3 (mm)	1150/170/55 685 (customizable in various sizes such as 685, 600, 540, etc.) 110 90 40
Front and rear straight channel width (pallet is 1200 length × 1000 width) Width of right-angle turning channel (pallet is 1200 length × 1000 width) Width of single-side loading and unloading channel (pallet is	Ast (mm) Ast (mm)	1200 2200 2400
1200 length × 1000 width) Turning radius (including safety edge) Travel speed, full/empty Lifting speed, full/empty	Wa(mm) m/s mm/s	1500 1.0/1.5 40/50 50/40
Maximum climbing ability, full/no load (S2-5min) Cross-channel capability Navigation Whether it supports outdoor operation Positioning accuracy	%(tanθ) mm Laser SLAM na	5/10 self of the self of the
Tire type, drive side/load side Tire size, load side Tire size, drive side Balance wheel size Number of wheels, front/rear (x = drive wheels)	mm mm	electromagnetic Polyurethane φ80°70 φ210°75 φ72°23 1x+4/4 470
Wheelbase, load-bearing side Driving motor power (servo motor) Lifting motor power, (S3-10%) (DC compound excitation)	mm kw kw	520 1 0.8 Electric steering (servo)
Steering motor (servo motor) Waterproof and dustproof level Operating temperature Storage temperature	-20°C~65°C	0.4 V-resistant; corrosion-resistant
	5~40°C (Indoo	r)
4G 5G Traffic quota WIFI	Support, FDD B1/B3/B5/B8, TDD B38/39/30/41 Support, 5G module needs to be customized 2G per robot per month Wifi module (AP6256) 2.4G&5GHz, supports 802.11a/b/g/n/ac protocols Bluetooth 5.0, BLE	
Android 11+ Linux(Ubuntu)		
Navigation laser*1 Obstacle avoidance laser*2 Fork tip obstacle avoidance laser*1 Depth camera*2 RGB camera*2 IMU	Detection rang Detection rang FOV: H 72°(±3° 215° FOV, reso 6DOF; rate dyn	e: 360°, detection distance: 0.05 ~ 40m e: 200°, detection distance: 0.05 ~ 40m e: 180°, detection distance: 0.05 ~ 12m ') V 50.5°(±3°), detection distance: 0.3 ~ 4m lution 1280°720 amic range: ±2000dps; accuracy: 0.01 degrees
Battery	odometer Charging voltage: 24V capacity:100Ah Endurance: 7-8 hours of deployment of charging piles to achieve 7*24h service Charging method: automatic/manual Battery weight: 30kg Battery type: Lithium iron phosphate 0%-100% charging time: 2.5 hours	
Charging Station	For details on charging piles, please see the "Charging piles" table Dimensions (H*W*D): 370mm*292mm*395mm Weight: 30kg Input: 100-240V ac ~ 50/60 Hz Output: 24V dc == 25-50A	
	Rated load Vehicle weight (including battery) Vehicle length (including safety edge) Vehicle width (including safety edge) Navigator bracket reference height Load center distance Loading distance (load-bearing length) Wheelbase Fork size Fork outer distance Lifting height Minimum height of fork surface from ground Minimum ground clearance (when fork raised) Front and rear straight channel width (pallet is 1200 length × 1000 width) Width of right-angle turning channel (pallet is 1200 length × 1000 width) Width of single-side loading and unloading channel (pallet is 1200 length × 1200 length × 1000 width) Turning radius (including safety edge) Travel speed, full/empty Lowering speed, full/empty Lowering speed, full/empty Lowering speed, full/empty Maximum climbing ability, full/no load (\$2-5min) Cross-channel capability Navigation Whether it supports outdoor operation Positioning accuracy Braking method Balance wheel size Number of wheels, front/rear (x = drive wheels) Track width, drive side Bhalance wheel size Number of wheels, front/rear (x = drive wheels) Track width, drive side Wheelbase, load-bearing side Driving motor power, (\$3-10%) (DC compound excitation) Steering motor power, (\$5-10%) (DC compound excitation) Steering system Charging temperature Charging temper	Vehicle weight (including safety edge) Vehicle length (including safety edge) Vehicle length (including safety edge) Vehicle width (including safety edge) Vehicle vehic

control	Chassis CPU	ARM® Quad-core Cortex-A76 2.4Ghz + ARM® Quad-core Cortex-A55 1.8Ghz
	Screen CPU	ARM® Quad-core Cortex-A55 2.0Ghz
	Chassis GPU	Mali-G610
	Screen GPU	Mail-G52
	Chassis memory	RAM: 8GB dual-channel LPDDR4; ROM: 64GB high-speed eMMC
	Screen Memory	RAM: 2GB dual-channel LPDDR4; ROM: 16GB high-speed eMMC
	Image Processing	Support OpenGL ES 1.1/2.0/3.0, OpenCL1.2, DirectX11
		Built-in high-performance 3D acceleration hardware
		H.264/H.265/VP9 up to 4Kx2K@60fps H.264/H.265 decoder supports 10bit decoding
		1080P multi-format video decoding, support H.264, VP8 and MVC
Interaction	Indicator Lights	led
	Speaker (voice module)	2
	Blue light	With clearance lights
	Emergency stop button	2 support TTS/audio stream output
Safety	Anti-collision strip	Bottom front + bottom side
	Pallet arrival detection	Rear fork root
Extensions	Peripherals	Elevators, automatic doors, notification lights and speakers, pagers, pads, follow-up bracelets, rollers,
		shelves, pallets
Software related	Mini Programs, APPs	WeChat remote management, the applet can realize functions such as issuing robot task instructions, map
	Robot Management Big Data Cloud Platform	Robot user rights allocation and business management; operational data analysis
	Remote monitoring platform	Real-time status monitoring of robots; real-time fault alarm and remote processing;
	Remote deployment management platform	Remote deployment is possible, and the robot can remotely scan and edit the map
	Remote dispatch management platform	Remote cross-space scheduling
	Real-time data visualization screen	Display the real-time status and operation statistics analysis of robots under different businesses



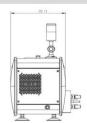


	ATEAGO ROBOTIKS L1 Forklift Automatic Charging Station
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picture	
picture	
Electrical parameters	
Input voltage	100-240Vac, ±20%
Input voltage frequency Charging voltage	50/60Hz, ±5Hz 24Vdc
Charging Voltage Charging Current	25~50A
Charging power	1.2kW
efficiency	≥92%@220Vac50-100%Load (up to 93%)
Power Factor	≥0.95@220Vac50-100%Load
Harmonic current THD	≤5%
Voltage stabilization	≤±1%
accuracy Steady flow accuracy	 ≤±1%
Input and output	
interface	
Input power cord	9A AC power cord, 3 meters long (including internal wiring length)
input power cord	or the power sora, o meters long (moraling method mining longury
Automatic charging port	100A copper diode brush block
Manual charging port	50A Anderson plug connector, gray, cable length 3 meters (including internal wiring length)
Communication Port	Joba Anderson plag connector, gray, cable length 5 meters (including internal willing length)
Communication with	
BMS	none
	CAN Bus (can communicate with the battery)
Reserved Ports	RS485 one channel (optional to Wi-Fi module)
Human Machine	One Ethernet port (to connect to the backend system)
Interface	
touchscreen	4.3 inches
Indicator Lights	Green: Standby/Full charge
	Yellow: Charging
Machaniael maranastara	Red: Fault
Mechanical parameters Install	Floor-standing
Dimensions (H*W*D)	370mm*292mm*395mm
Brush block extension	
stroke	No extension (customizable)
Height of brush block	Height 130mm, fine-tuned by foot cup ±30mm
center from ground Protection level	IP20
Cooling method	Forced cooling
Environmental	n oroca cooming
parameters	
Operating temperature	'-20℃ ~ 45℃
Storage temperature	'-40°C ~ 70°C
Operating humidity	0 ~ 95%, no condensation
Altitude Protection function	≤2000m
Emergency stop button	Press to stop charging, rotate to reset
Leakage protection	AC type leakage protection
Communication	When charging is set to CAN communication, if the communication is interrupted or timed out for 5s,
interruption protection	charging will stop
	Input over-voltage and under-voltage protection, output over-voltage protection, output over-current
General protection	protection, short circuit protection, grounding protection, over-temperature protection, telescopic motor
	stall protection, battery anti-reverse protection

Charger size









ATEAGO ROBOTIKS Technology Co., Ltd

Hangzhou Dige Technology Co., Ltd

Web: http://www.ateago.com/

Add: F3, Building NO.2, Dayuan Road NO.1188, Qingshan Lake Street, Linan District, Hangzhou, 311305, China