ATEAGO S8-150 Delivery Robot Chassis Dispatching AGV AMR With Auto-lifting Picture 310(<u>mm</u>) Height 740<u>*500 (mm)</u> Size Basics Weiaht 72ka Exterior material ABS, Sheet Metal Shelf Standard: 660*700*325 (mm) or customize the shelf Rated load 150kg Carrier Lifting height 50mm Whole body IP43, battery IP66 -10°C~65°C; UV resistance; Corrosion resistant -20°C~65°C Lifting speed 5mm/s Water-proof & Dust-proof Operating temperature **Use Environment** Storage temperature 5~40°C (indoor) Charging temperature Terminal control (cloud, PC, mobile, PAD) without screen Display&touch Support FDD B1/B3/B5/B8,TDD B38/39/30/41 5G Supported, need to add 5G accessories Data quota 2G/ month for each robot Network Communication WIFI Wifi module (AP6256) 2.4G&5GHz, support 802.11a/b/g/n/ac protocal Bluetooth Bluetooth 5.0, BLE os Linux(Ubuntu) iDAR1 Detection zone: 360°, Detection range: 0.02~40m LiDAR2 Detection zone: 140°, Detection range: 0.02~12m Sensors RGB camera 215°FOV, resolution 1280*720 IMU 6DOF; Rate dynamic range: ±2000dps; Precision: 0.01° Wheel speed indicator odometer Charging voltage: 24V Capacity: 30000mAh Battery life: 10h Battery Use charging pile to achieve 7*24h service Charging & The time it takes to fully charge: 5.5h **Battery life** Working voltage: 100~240VAC. 50/60Hz Adapter Dimension: 375mm*160mm*355mm Weight: 4.35kg Charging pile nput: 100-240V~50/60 Hz Output: 29.4V==7.0A Chassis CPU ARM® Quad-core Cortex-A72 1.5Ghz Chassis GPU VideoCore VI Chassis memory RAM: 4GB binary channels LPDDR4; ROM: 32GB High speed eMMC Support OpenGL ES 1.1/2.0/3.0,OpenCL1.2,Directx11 Control Embedded high performance 3D acceleration hardware H.264/H.265/VP9 up to4Kx2K@60fps Picture processing H.264/H.265 The decoder supports 10bit decoding 1080P multi-format video decoding, support H.264, VP8 and MVC indicator light ED (Programmable, support segmented control) Emergency stop Other firmware 4Ω10W Loudspeaker Supports TTS/ audio stream output Velocity 1.2m/s Adjustable It can be used in qualified parks/industry zones Whether support outdoor operation Obstacle climbing 20mm Slope climbing Movement Floor gap width 35mm The narrowest width of the robot path needs to be not less than 70cm Passage width Elevator width 70cm+ 70cm+ Gate width Positioning Accuracy ±5(mm)/±1(°) APP remote management. Use the app program to send robot task, visualize task statistics APP functions. Robot management platform Authorization allocation and business management of robot users; Operational data analysis Real-time status monitoring; Real-time fault alarm and remote processing Remote monitoring platform Software The robot can be deployed via remote mapping. Operators can scan and edit the map Remote deployment management platform remotely Remote scheduling management platform Remote cross-space scheduling Real-time data visualization Display real-time status and operational statistical analysis of robots in different businesses.