ATEAGO S7-80 Delivery Robot Specs		
Image		
Basic Parameters	Height Length*Width Weight Exterior material	1240 (mm) 550°500 (mm) 58kg Flame Resistance ABS
Load Device	Box configuration Single layer height	4 layers (can be combined and adjusted into 2-layer, 3-layer, 4-layer) 4 layers: 190mm, 190mm
	Detachability Size Load capacity	Detachable layers 500*424mm 80kg
Operating environment	Waterproof and dustproof grade Operating temperature Storage temperature	Whole body: IP43; Battery: IP66 -10 °C ~ 65 °C; UV resistance; Corrosion resistant -20°C~65°C
Dianlay	Charging temperature 10.1-inch screen, MIPI interface, resolution 1280*720	5~40°C (indoor)
Display	4G	supported,FDD B1/B3/B5/B8,TDD B38/39/30/41
Network	5G	Support, need to add 5G accessories
Communicatio n	Traffic quota WIFI	Each robot is 2G/month Wifi module (AP6256) 2.4G&5GHz, support 802.11a/b/g/n/ac protocal
"	Bluetooth	Bluetooth 5.0, BLE
OS	Android 11+ Linux(Ubuntu) Lidar*1	Detection Range: 360°, Detection Distance: 0.02 to 40 m
Sensors	Depth Camera	FOV: H 72°(±3°) V 50.5°(±3°), Detection Distance: 0.4~2m
	RGB Camera	215°FOV, Resolution1280*720
	IMU Wheel Speed Sensor	6 DOF; Rate Dynamic Range: ±2000 dps; Accuracy: 0.01° odometer
	wheel speed sensor	Charging voltage: 24V
Charging & Battery Life	Battery	Capacity: 15Ah Duration: 10h Z*24h service can be achieved with the charging pile. Time to fully charge: 2.5 hours
	Adapter	Working voltage: 100°240VAC, 50/60Hz
	Charging pile	Size: 375mm*160mm*355mm Weight: 4.35Kg Input: 100-240V~50/60 Hz Output: 29.4V=7.0A
Control	Chassis CPU	ARM® Quad-core Cortex-A72 1.5Ghz
	Screen CPU Chassis GPU	ARM® Quad-core Cortex-A55 2.0Ghz VideoCore VI
	Screen GPU	Mail-G52 GPU
	Chassis Memory	RAM: 4GB Dual channel LPDDR4; ROM: 32GB High speed eMMC
	Screen Memory Image Processing	RAM: 2GB Dual channel LPDDR4: ROM: 16GB High speed eMMC         Support OpenGL ES 1.1/2.0/3.0,OpenCL1.2,Directx11         Embedded high-performance 3D acceleration hardware         H.264/H.265/VP9 up to4Kx2K@60fps         H.264/H.265; The decoder supports 10bit decoding         1080P multi-format video decoding, supporting H.264, VP8 and MVC
Other	Ambient lighting	LED
Firmware	Emergency button	1 POTEW supports TEC / surface to starts
Performance	Loudspeaker Velocity Navigation Mode	8Ω15W, supports TTS/ audio stream output         0.3-1.2m/s (adjustable)         Free Navigation / Track Navigation / Mixed Navigation / Follow         Humbher during the breat of the protocol
	Whether support outdoor operation Obstacle climbing Slope climbing Floor gap width	It can be used in the park zone that meets certain requirements. 20mm 8° 35mm The parking width of the rebet should be an insetted 70mm.
	Passage width Elevator width	The passing width of the robot should be no less than 70cm No less than 70cm
	Gate width	No less than 70cm
	Positioning Accuracy	±5(mm)/±1(°)
Expansion Software	Peripherals	Elevator, automatic door, notification light and speaker, call button, follow wristband, roller, box, shelf
	Mini Program, App Robot Management Big Data Cloud Platform	Remote management via WeChat, allows task command issuance, map editing, and task statistics visualization without installation User permissions and business management; Operational data analysis
	Remote Monitoring Platform	Real-time robot status monitoring; Fault real-time alarms and remote handling
	Remote Deployment Management Platform	Remote deployment, robot remote scanning, and map editing
	Remote Scheduling Management Platform	Remote cross-space scheduling
	Real-time Data Visualization Screen	Displays real-time robot status and operational statistics under different business scenarios