Date 12006.05.18

DISTANCE MEASURING TYPE OBSTACLE DETECTOR

UBG-05LN

Specifications



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1. Outline

1. Operating Principle

UBG-05LN is an obstacle detection sensor with 785nm wavelength laser light source. It detect objects in the predefined area by scanning 180鱠 semicircle and calculates the coordinates of the detected object by measuring its distance and angle. The product is laser class 1 safe.

2. Area Setting

31 different area patterns and their coordinate points can be set using application software and serial communication RS232C.

3-step outputs can be selected for each area.

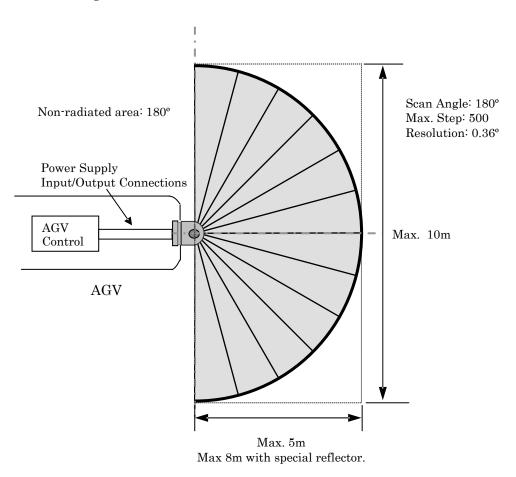
3. Area Switching

Bit input at terminal points switches the predefined area patterns.

4. Malfunction Output

Self-diagnostic functions continuously check laser radiation and motor rotation and supplies malfunction output upon error detection.

2. Structure (Scan Image)



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Model UBG-05LN
Laser safety Class 1 (FDA) Laser power:0.8mW or less(Scanning satishfies the laser Class 1 safety.) Power source 24V DC ±10% (Startup voltage range 18~30V) Current consumption Detection distance 100mm ~5000mm* (White sheet 125×125 mm or more) 100mm ~ 8000mm* (Specific reflector 250×250 mm or more) Accuracy Distance 100 ~ 1000mm* ±20mm* Distance 1000 ~ 4000mm ±2% of measurement* Repeatability ±10mm* Hyteresis Values specified while setting area patterns (Default: 6.25%) 6.25% of detection distance (not less than 60 mm) 3.17% of detection distance (not less than 30 mm) Outputs Photo coupler open collector output (DC 30V, 50mA max.) Output 1: Turns OFF during object detection inside area. Output 2: Turns OFF during object detection inside area. Output 3: Turns OFF during object detection inside area. Malfunction Output: Always ON during normal operation. (Note: All the outputs turn OFF during malfunction) Scan Angle 180°(Resolution 0.36°) Scan Time Output Less than 210 msec (Note: Additional delay of max. 100 msec (1 scan time) will occurduring area switching) Start up Time Light Display Within 10 sec after power supply. (Varies with startup conditions) Power supply (Green): Flashes during object detection inside area Output 1 (Orange): Switches on during object detection inside area Output 1 (Orange): Switches on during object detection inside area Output 1 (Orange): Switches on during object detection inside area Output 3 (Orange): Switches on during object detection inside area Output 3 (Orange): Switches on during object detection inside area. Output 3 (Orange): Switches on during object detection inside area. Output 3 (Orange): Switches on during object detection inside area. Output 3 (Orange): Switches on during object detection inside area. Output 3 (Orange): Switches on during object detection inside area. Output 3 (Orange): Switches on during object detection inside area. Output 3 (Orange): Switches on during object detection inside area. Output 3 (Orange): Switches on during object d
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$\begin{array}{ccc} & \text{Output 3 (Orange): Switches on during object detection inside area.} \\ \hline \text{Connection} & \text{Flying lead cable (1m)} \\ \hline \text{Ambient Light} & \text{Halogen/Mercury light: } 10000\text{Lx or less} \\ \hline \text{Resistance} & \text{Fluorescent Light: } 6000 \text{ Lx (max.)} \\ \hline \text{(Note: Direct sunlight or strong light source may cause misdetections)} \\ \hline \text{Ambient Conditions} \\ \hline \text{Temperature:} & -10 \sim 50^{\circ}\text{C} \\ \hline \end{array}$
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Ambient Light Resistance Halogen/Mercury light: $10000 Lx$ or less Fluorescent Light: $6000 Lx$ (max.) (Note: Direct sunlight or strong light source may cause misdetections) Ambient Conditions Temperature: $-10 \sim 50^{\circ}C$
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Unmidity: 1 050% on loss (non-sondon sing)
Humidity: 85% or less (non-condensing)
Storage temperature $-25 \sim 75^{\circ}$ C
Vibration Resistance Double amplitude 1.5mm 10 ~ 55Hz, 2 hours XYZ direction, and
$98\text{m/s}^2 \times 55\text{Hz} \sim 200\text{Hz}$ in 2 minutes sweep, 1 hours in XYZ directions
Impact Resistance 196 m/s ² (10G), 10 times in XYZ directions
Weight Approx. 185g (260g with cable)
Protection Class IP64
Case Front: Polycarbonate / Back: ABS
External dimension 60 W×60 H×75 D mm *Under standard test conditions

^{*}Under standard test conditions.

刋 瘠	UBG-05LN Specifications	呕 燄	C - 42 - 3404	3髞7
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Specifications (con Area Setting	Output1 setting: Area with maximum 7 points form 0 to 5000mm							
8	Output2 set	_	aight	1				
	1	_	Shape					
	area poin	ts						
	: Percentage of Output1 area points Output3 setting: Same as Output2							
Inputs and Area	Photo coupler input (Anode common, supply current to switch or							
Selection	inputs = 4m			,	PP-J			
		,						
	Area Switch	ing:						
		-	[Input1]	Input2] [1	nput3][In	put4][Input5]		
	Laser radiat		_	_	p 4.00][111	b are 11[111b aree]		
	High: OFF			I				
	Low: ON							
		[0, 1]	[a to]	[T 44]	[T]	TA TD //		
	[Input1] ON	[Input2] ON	[Input3] ON	[Input4] ON	[Input5] ON	Area Patterns Laser OFF		
	OFF	ON	ON	ON	ON	Area 1		
	ON	OFF	ON	ON	ON	Area 2		
	OFF	OFF	ON	ON	ON	Area 3		
	ON	ON	OFF	ON	ON	Area 4		
	OFF	ON	OFF	ON	ON	Area 5		
	ON	OFF	OFF	ON	ON	Area 6		
	OFF	OFF	OFF	ON	ON	Area 7		
	ON	ON	ON	OFF	ON	Area 8		
	OFF ON	ON OFF	ON	OFF OFF	ON	Area 9		
	OFF	OFF	ON ON	OFF	ON ON	Area 10 Area 11		
	ON	ON	OFF	OFF	ON	Area 12		
	OFF	ON	OFF	OFF	ON	Area 13		
	ON	OFF	OFF	OFF	ON	Area 14		
	OFF	OFF	OFF	OFF	ON	Area 15		
	ON	ON	ON	ON	OFF	Area 16		
	OFF	ON	ON	ON	OFF	Area 17		
	ON	OFF	ON	ON	OFF	Area 18		
	OFF	OFF	ON	ON	OFF	Area 19		
	ON OFF	ON ON	OFF OFF	ON ON	OFF OFF	Area 20 Area 21		
	ON	OFF	OFF	ON	OFF	Area 21 Area 22		
	OFF	OFF	OFF	ON	OFF	Area 23		
	ON	ON	ON	OFF	OFF	Area 24		
	OFF	ON	ON	OFF	OFF	Area 25		
	ON	OFF	ON	OFF	OFF	Area 26		
	OFF	OFF	ON	OFF	OFF	Area 27		
	ON	ON	OFF	OFF	OFF	Area 28		
	OFF	ON	OFF	OFF	OFF	Area 29		
	ON	OFF	OFF	OFF	OFF	Area 30		
	OFF	OFF	OFF	OFF	OFF	Area 31		
out Response Time	me Input reading frequency: 1 scan time (100msec) (Note: Input reading frequency is 1msec when Laser is switch							

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4. Lead cable color and signals

Color	Signal				
Black	Output1				
White	Output2				
White (Blue)	Output3				
Orange	Malfunction Output				
Gray	Output common minus				
Red	Input common plus				
Green	Input1				
Yellow	Input2				
Purple	Input3				
White (Yellow)	Input4				
White (Purple)	Input5				
Brown	+V IN				
Blue	-V IN				
Yellow (Red)	Serial Input (RXD)				
Yellow (Green)	Serial Output (TXD)				
Yellow (Black)	Serial Ground (GND)				

Note:

- 1. Leave the unused input terminals open or connect to input common plus (red).
- 2. Leave the unused output terminals open or connect to input common minus (gray).
- 3. Colors inside () suggest wires with colored lines on either sides.

5. Installation Notice

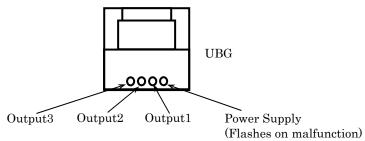
When mounting the device make sure to provide sufficient space for light window. Sensor will not operate normally if its view is blocked leading to serious injuries or property damage.

Note For Long Term Use:

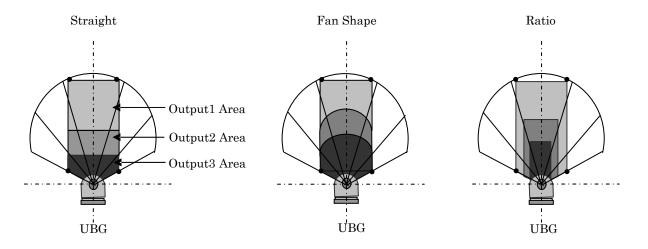
It is necessary to readjust/reset sensors operating for more than one year to maintain the absolute accuracy.

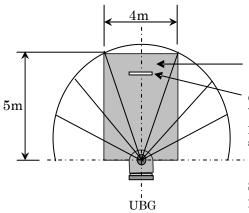
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6. Light Display Position



7. Area Setting Range and Shape





Area Setting Range

OBJECT:

White Kent sheet 300×300 mm placed perpendicular to the sensor's vertical axis within $100\sim5000$ mm from sensor axis

Or

Specific Reflector 200×200mm placed perpendicular to the sensor's vertical axis within 100~8000mm form sensor axis

