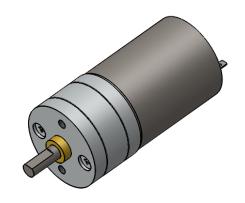
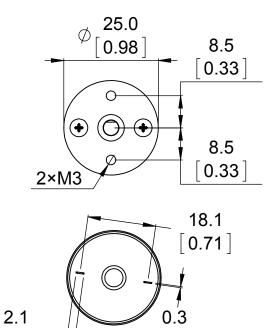
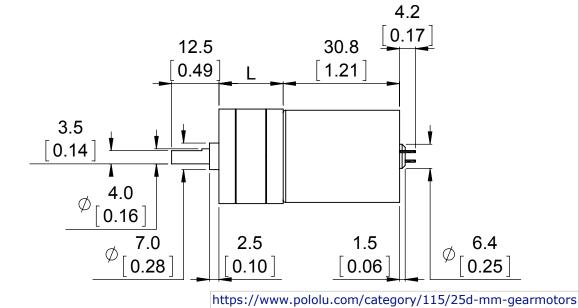


L
17 mm [0.68 in]
17 mm [0.68 in]
19 mm [0.75 in]
21 mm [0.83 in]
21 mm [0.83 in]
23 mm [0.91 in]
23 mm [0.91 in]
25 mm [0.98 in]
25 mm [0.98 in]
27 mm [1.06 in]
27 mm [1.06 in]







1. To get the specified scale, select 100% in print settings.

[0.01]

[80.0]

Drawing date: 15 January 2016

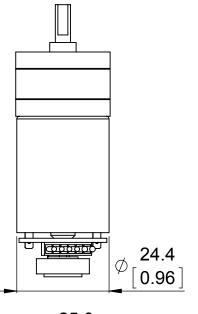
Units: mm | Material: [in] | Material

Robotics & Electronics
© 2016 Pololu Corporation

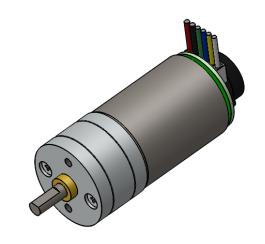
25D mm Metal Gearmotors (without encoders)

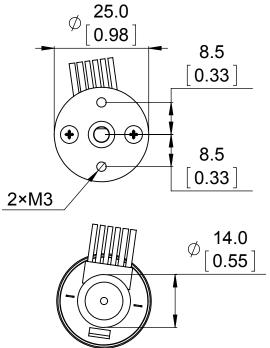
mix

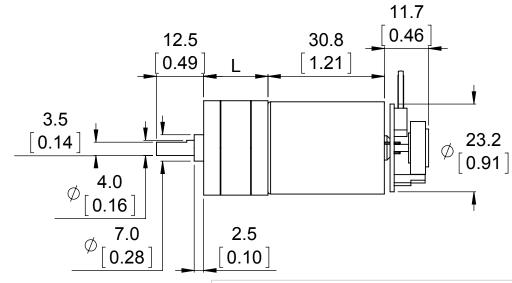
Scale: 1:1



Gear ratio	L
4.4:1	17 mm [0.68 in]
9.7:1	17 mm [0.68 in]
20.4:1	19 mm [0.75 in]
34:1	21 mm [0.83 in]
47:1	21 mm [0.83 in]
75:1	23 mm [0.91 in]
99:1	23 mm [0.91 in]
172:1	25 mm [0.98 in]
227:1	25 mm [0.98 in]
378:1	27 mm [1.06 in]
499:1	27 mm [1.06 in]







https://www.pololu.com/category/115/25d-mm-gearmotors

25D mm Metal Gearmotors (with encoders)

Drawing date: 15 January 2016

Units: mm [in]

Material: mix

Robotics & Electronics © 2016 Pololu Corporation

1. To get the specified scale, select 100% in print settings.

Scale: 1:1