JAGUAR 4X4 WHEEL







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JAGUAR 4X4 WHEEL

COMPLETE SYSTEM



Jaguar-4x4-wheel Mobile Robotic Platform is designed for indoor and outdoor operation requiring higher ground clearance and faster maneuverability. Jaguar-4x4-wheel platform is a wheeled version of the Jaguar-Lite platform. Jaguar-4x4-wheel is driven by four powerful (80W) motors, one for each wheel. Jaguar-4x4-wheel platform is rugged, light weight (< 20Kg), fast (max 15km/hr), with high ground clearance (88mm), compact, weather and water resistant. It is designed for tough terrains and capable of running over vertical step up to 155mm and climbing up low rise stairs (up to 110mm step). Jaguar-4x4-wheel is fully wirelessly (802.11G) connected. It integrates outdoor GPS and 9 DOF IMU (Gyro/Accelerometer/Compass) for autonomous navigation. The integrated high resolution video/audio and laser scanner (optional) provide remote operator detail information of the surrounding. Besides the ready to use control and navigation software, a full development kit including SDK, data protocol and sample codes, is also available.

Key Features



Rugged and reliable mobile platform for indoor and outdoor applications with faster maneuverability (max 15Km/hr)



Indoor and outdoor operation requiring higher ground clearance and on tough terrains



Weather and water resistant enclosure



Light weight (< 20Kg) and compact design with large payload

Climbing up > 45° slope and stairs (max 110mm or 4.5")



Autonomous navigation with outdoor GPS and 9 DOF IMU (Gyro/Accelerometer/Compass)



Managing max 155mm (6") vertical step (obstacle)

Mobility

Terrain: Sand, rock, concrete, gravel, grass, soil and others wet and dry

Slope: > 45°

Maximum vertical step: 155mm (6")

Stair climbing: Max stair step height 110mm (4.5")

Traverse: > 200mm (8") Speed: 0 - 15Km/hr

Turning radius: 0, min 750mm (29.5") diameter of turning space

Ground clearance: 88mm (3.5")

Operator remote control

Autonomous navigation with GPS and 9 DOF IMU (Gyro/Accelerometer/Compass) Indoor vision landmark GPS (Optional)

Survivability

Sealed weather resistant enclosure

Temperature: -30° to +50° Shock resistant chassis

Drop to concrete: Max: 1200mm (4ft) Rated: 900mm (3ft)

Electronics

Motion and sensing controller (PWM, Position and Speed Control) 5Hz GPS and 9 DOF IMU (Gyro/Accelerometer/Compass)

Laser scanner (4m or 30m) (Optional)

Temperature sensing & Voltage monitoring

Headlights

Video / Audio

Color Camera (640x480, 30fps) with audio

Communication

WiFi802.11G (Optional WiFi 802.11N) Ethernet (Optional)

External Auxiliary Ports

Ethernet (Optional)

General purpose communication and power port (Optional)



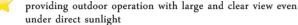
Surviving max 1200mm (4ft) drop to concrete



Integrated Laser scanner (Optional) Integrated high resolution video camera with audio



All 802.11G (optional 802.11N) wirelessly connected Head mounted display (optional) and Gamepad controller





Ready to use control and navigation software

Full development kit including SDK, data protocol and sample codes, supporting Microsoft® Robotics Studio, Microsoft® Visual Studio, NI LabVIEW®, MATLAB®, Java®

Operator Control Unit

Gamepad Controller

Head mounted display (dual 640 x 480), equivalent to 60" display viewed in 2.7m (9 feet) (Optional) Portable computer (Optional)

Power

Rechargeable battery: LiPo 22.2V 10AH LiPo battery charger with balancer

Nominal operation time: 2 hours (Optional 4 hours)

Motor

Wheel Motors (24V): 4 units

Max output (after gear down) (x4): Max 80W, 65Kg.cm/wheel Rated current: 2.75A, Max current: 16A

Dimensions

Height: 255mm (10") Width: 530mm (21") Length 570mm (22.5")

Weight: 19.5Kg (Standard Configuration)

Payload

Carrying Payload (on flat surface): max 30Kg Dragging Payload (on flat surface): max 50Kg

Application Development

Full development kit including SDK, data protocol and sample codes, supporting Microsoft® Robotics Studio, Microsoft® Visual Studio, NI LabVIEW®, MATLAB®, Java®

Microsoft ROBOTICS STUDIO



















JAGUAR 4X4 WHEEL

CHASSIS



Jaguar-4x4-wheel Mobile Robotic Platform is designed for indoor and outdoor operation requiring higher ground clearance and faster maneuverability. Jaguar-4x4-wheel platform comes with everything that Jaguar-4x4-wheel robot has except the electronic components. Jaguar-4x4-wheel chassis is driven by four powerful (80W) motors (included), one for each wheel.

Key Features



Rugged and reliable mobile platform for indoor and outdoor applications with faster maneuverability (max 6.5Km/hr)



Indoor and outdoor operation requiring higher ground clearance and on tough terrains



Weather and water resistant enclosure



Climbing up > 45° slope or stairs (max 110mm or 4.5")

Mobility

Terrain: Sand, rock, concrete, gravel, grass, soil and others wet and dry

Slope: > 45°

Maximum vertical step: 155mm (6")

Stair climbing: Max stair step height 110mm (4.5")

Traverse: > 200mm (8")Speed: 0 - 6.5Km/hr

Turning radius: 0, min 750mm (29.5") diameter of turning space

Ground clearance: 88mm (3.5")

Survivability

Sealed weather resistant enclosure Temperature: -30° to +50° Shock resistant chassis

Drop to concrete: Max: 1200mm (4ft) Rated: 900mm (3ft)



Light weight (< 15Kg) and compact design with large payload capacity



Managing max 155mm (6") vertical step (obstacle)



Surviving max 1200mm (4ft) drop to concrete



Four 24V DC motors with integrated encoder (with max output power 80W/motor)

Motor

Wheel Motors (24V): 4 units

Max output (after gear down) (x4): Max 80W, 65Kg.cm/wheel Rated current: 2.75A, Max current: 16A

Dimensions

Height: 255mm (10") Width: 530mm (21") Length: 570mm (22.5")

Weight: 14.5Kg (Standard Configuration)

Payload

Carrying Payload: max 34Kg Dragging Payload: max 54Kg







