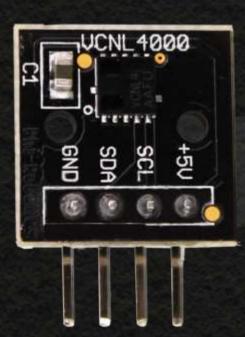


Product Manual



VCNL4000-BB

Version 1.1

Phi Robotics Research Pvt. Ltd.

www.phi-robotics.com

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1 Introduction

VCNL4000-BB is a compact IR proximity and ambient light sensor breakout board. It can detect any obstacle within a range of about 20 cm. Proximity data and ambient light level data are read over I2C interface.

2 **Board Features**

- On-board 3.3V regulator
- Built-in ambient light sensor
- Adjustable IR LED pulse current

3 Specifications

- Input voltage: 5V
- IR LED pulse current: 10 mA 200 mA Obstacle detection range: 20 cm
- Ambient light resolution: 0.25 lx
- I2C slave address: 0x26

3.1 PCB Details

- PCB type: FR4
- Solder mask: Black
- Board thickness: 1.6mm
- Surface finish: Immersion gold

4 Hardware Connections

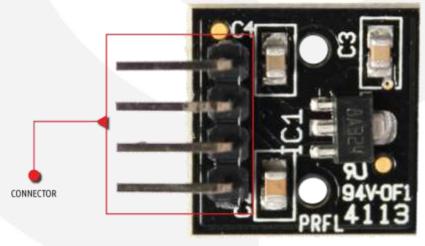


Figure 1-VCNL4000-BB bottom view

VCNL4000-BB has 4 pin male berg connector. The header has supply pins and I2C pins for interfacing with microcontroller. I2C slave address of VCNL4000 is 0x26, so read and write addresses are 0x26 and 0x27 respectively. Figure 2 shows pin layout for VCNL4000-BB.

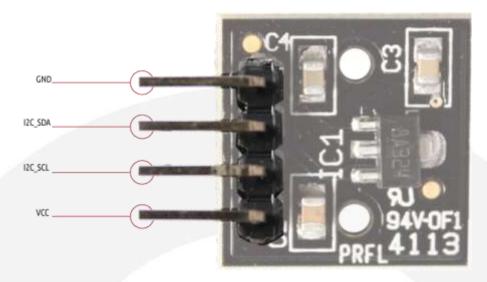


Figure 2-VCNL400-BB pin layout

5 Pseudo Code

5.1 Register Addresses and Bit Values for Flags

// VCNL4000 I2C slave address VCNL_SLAVE_ADDR = 0x26 // VCNL4000 register addresses VCNL_REG_CMD = 0x80 VCNL_REG_AMB_DATA_H = 0x85 VCNL_REG_AMB_DATA_L = 0x86 VCNL_REG_PROX_DATA_H = 0x87 VCNL_REG_PROX_DATA_L = 0x88 // VCNL4000 command register flag values VCNL_START_AMBIENCE_CONVERSION = 0x10 VCNL_START_PROXIMITY_CONVERSION = 0x08 VCNL_AMBIENCE_DATA_READY = 0x40 VCNL_PROXIMITY_DATA_READY = 0x20

5.2 Reading VCNL4000 Register

```
uint8_t vcnlReadRegister(regAddr)
     uint8 t data;
     // I2C start signal
     i2cStart();
     // send VCNL4000 I2C slave address with R/W bit set as
     i2cWriteByte(VCNL SLAVE ADDR);
     // send register address to read
     i2cWriteByte(regAddr);
     // I2C repeated start signal
     i2cStart();
     // send VCNL4000 I2C address with R/W bit set as 1 \,
     i2cWriteByte(VCNL_SLAVE_ADDR | 0x01);
    // read a byte from I2C
     data = i2cReadByte();
     // I2C stop signal
     i2cStop();
     return data;
```

5.3 Writing VCNL4000 Register

void vcnlWriteRegister(uint8 t regAddr, uint8 t data)

```
// I2C start signal
i2cStart();
// send VCNL4000 I2C slave address with R/W bit set as 0
i2cWriteByte(VCNL_SLAVE_ADDR);
// send register address to write
i2cWriteByte(regAddr);
// write data byte
i2cWriteByte(data);
// I2C stop signal
i2cStop();
```

}

{

{

5.4 Reading Ambient Light Value

```
uint16 t vcnlGetAmbience(void)
     uint16 t data;
     uint8 t temp, cmd;
     // read VCNL4000 command register
     // OR the new command with read data
     cmd = vcnlReadRegister(VCNL REG CMD);
     cmd |= VCNL START AMBIENCE CONVERSION;
     // write new command to VCNL4000
     vcnlWriteRegister(VCNL REG CMD, cmd);
     // wait for proximity conversion to complete
     do
        temp = vcnlReadRegister(VCNL REG CMD);
     }while( !(cmdReg & VCNL AMBIENCE DATA READY) );
     // read ambience data high byte
     temp = vcnlReadRegister(VCNL REG AMB DATA H);
     data = temp << 8;</pre>
     // read ambience data low byte
     temp = vcnlReadRegister(VCNL_REG_AMB_DATA L);
     data |= temp;
     return data;
```

{

{

Reading Proximity Distance Value 5.5

```
uint16_t vcnlGetProximity(void)
     uint16 t data;
     uint8 t temp, cmd;
     // read VCNL4000 command register
     // OR the new command with read data
     cmd = vcnlReadRegister(VCNL REG CMD);
     cmd |= VCNL START PROXIMITY CONVERSION;
     // write new command to VCNL4000
     vcnlWriteRegister(VCNL REG CMD, cmd);
     // wait for min 400us after starting conversion
     // as mentioned in the datasheet
     delay us(400);
     // wait for proximity conversion to complete
     do
        temp = vcnlReadRegister(VCNL REG CMD);
     }while( !(cmdReg & VCNL PROXIMITY DATA READY) );
     // read proximity data high byte
     temp = vcnlReadRegister(VCNL REG PROX DATA H);
     data = temp << 8;</pre>
     // read proximity data high byte
     temp = vcnlReadRegister(VCNL REG PROX DATA L);
     data |= temp;
     return data;
```

}

6 Reference

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VCNL4000 Datasheet: <u>http://www.vishay.com/docs/83798/vcnl4000.pdf</u>

78L33 Datasheet: <u>http://in.mouser.com/Search/Refine.aspx?Keyword=78L33</u>

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