# Actuonix External RC Control Board • Ext -R

The Ext -R control board is an in-line, compact, lightweight, alternative to the LAC. This board has our standard RC input and position controller, making it compatible with most RC receivers, and a wide array of controllers such as Raspberry Pi, and Arduino.

In addition to position feedback-based stall protection, an adjustable potentiometer allows you to set a current limit between 0A and 1A. This can help increase the life of the actuator by limiting the maximum force the actuator will generate when over-loaded.

The board can be powered by the 3 wire RC connection, or by connecting an external supply to the extra pins. See connection diagram for more detail.

### **Specifications**

<b>Digital: RC Servo (PWM)</b> PWM with 1-2ms high time, 50-300Hz period, 5V amplitude
<b>12-bit Dual Sample Rate Quasi PD</b> Analog position and current signals accessible (F1, F2)
All Actuonix -P Actuators with position feedback, 6V or 12V (except PQ12) Controller configuration must be selected at time of order
36mm x 15mm x 6.7mm
6–12 VDC, 1A minimum Note: Supply voltage must match actuator's rated voltage
–10°C to +70°C at 10%–80% relative humidity

## Operation

The actuator will move to the commanded position when power and a valid control signal are applied. The control range is between 1000µs (full retract) and 2000µs (full extend). When the control signal is removed, the actuator will move to the last valid control position it received, then enter a low power mode. When the control signal resumes, normal operation will also resume.

Should the actuator be prevented from moving, due to overloading, impacting a hard stop, or current limiting, the stall protection mode will be activated. If the stall condition remains after a few seconds, the motor will be disabled. The commanded position must be changed (by a larger increment than usual), or the power cycled to exit the stall condition.

The current limit potentiometer adjusts the current limiting between 0A-1A and can be adjusted at any time. Turn the potentiometer counter-clockwise to increase the current limit and clockwise to lower the current limit.

F1 is an optional output giving access to the position feedback signal, which varies linearly between 0V-3.3V based on the position on the actuator -3.3V is fully retracted and 0V is fully extended. F2 is an optional output giving access to the current feedback signal, whose voltage is a 3.3:1 scaled representation of the actuator current – 0A would equate to 0V on F2, while 1A would equate to 3.3V.

Any connection made to F1 or F2 must be high impedance type, or actuator performance may be affected.







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#### **Model Selection**

The Ext-R is pre-configured to work with the selected actuator family. Make your selection based on the actuator you wish to connect to the Ext-R.



#### **External Connections Detail**

X1 Radio Control Receiver Connector				X2 Actuator Connector			X3 Feedback Connector		
Pin	Label	Function	Wire Colour	Pin	Function	Wire Colour	Pin	Label	Function
1	-	Ground	Black	1	Positive Reference	Yellow	1	F1	Position Feedback
2	+	6-12 VDC Power	Red	2	Motor	Black	2	F2	Current Feedback
3	S	RC / Hobby Servo Input Signal	White	3	Motor	Red			
4		No Internal Connection	Red	4	Position Feedback	Purple	P1 Current Limit Control		
5	-	Ground	Black	5	Negative Reference	Orange	Dire	ction	CurrentLimit
							C	W	Lower (0A min)



Top View – External Power Supply Connected



Top View – RC Receiver Power Only



CCW

Higher (1A max)

Bottom View – P1 Current Limit Control Potentiometer

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