

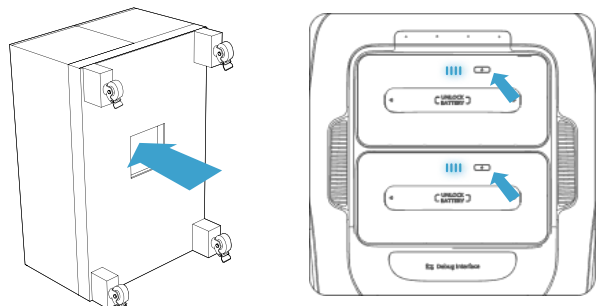


Unboxing 01

1 Battery Activation

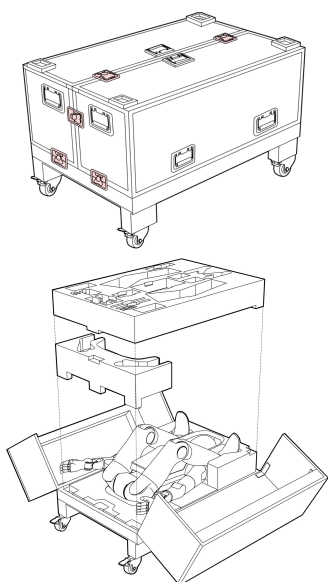
Upon first unboxing, or when the battery pack is in storage/transport mode

1. Place the packaging box upright and open the bottom access panel
2. Short press + long press the battery pack power button for 1 second; all indicator lights turning on indicates successful activation
3. Repeat the above steps for the second battery to ensure both batteries are activated



2 Lay the Packaging Box Flat on the Ground & Unbox

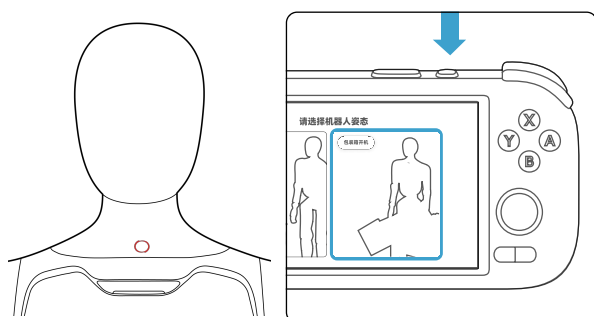
Open the top lid of the packaging box and remove the two foam pads



3 Initial Stand-Up

Do not touch the robot during automatic stand-up. Keep sufficient clear space around the box

1. Long press the main power button on the chest to power on
2. Long press the top power button for 3 seconds to turn on the remote control
3. Select 「Box Start-Up」; the robot will exit the box following guided instructions



- The legs automatically unfold from the folded position to a lying-flat position
- The legs retract, and the robot uses its arms for support to complete the stand-up

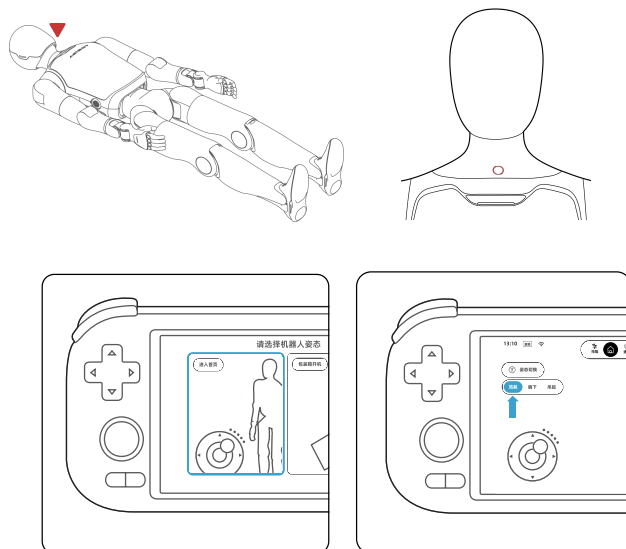
Routine Power On/Off 02

1 Daily Startup

For regular use, the initial unboxing setup is not required again. Simply power on the robot.

Do not touch the robot during automatic stand-up. Keep sufficient clear space around it

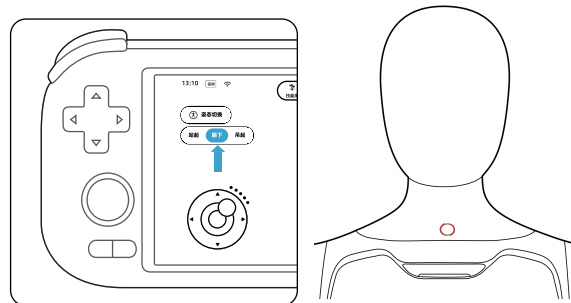
1. Place the robot lying flat on the ground
2. Long press the main power button on the chest for 3 seconds to power on
3. Connect the remote controller to the robot, go to the home page, and execute the stand-up action
4. Execute posture transition: Lie Down - Stand Up; wait for the robot to complete automatically



2 Routine Shutdown

Do not touch the robot while it is automatically lying down. Keep sufficient clear space around the robot.

1. Connect the remote controller to the robot
2. Use the remote to command the robot to lie down
3. Short press the power switch on the chest, and follow the voice prompts to shut down

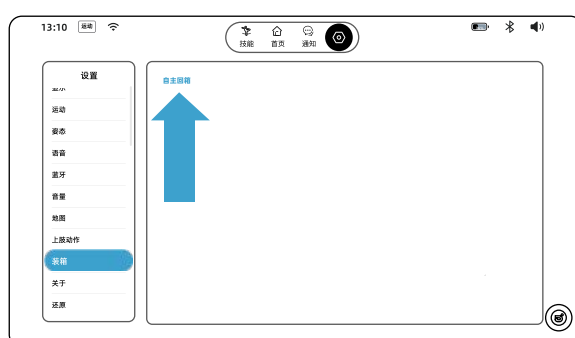


3 Packing (Return to the box)

Do not touch the robot while it is automatically lying down. Keep sufficient clear space around the robot.

When the robot is standing stably, follow these steps to safely pack it back into the box:

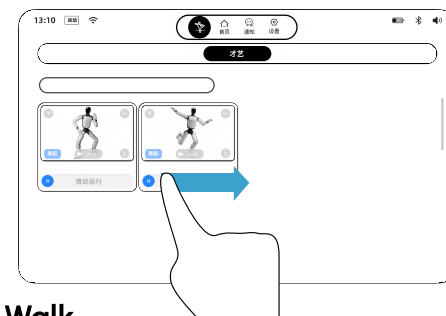
1. Open the remote controller, go to 「Settings」 → 「Packing」 → 「Auto Return to Box」
2. Follow the remote controller prompts to begin automatic box entry



Basic Operation 03

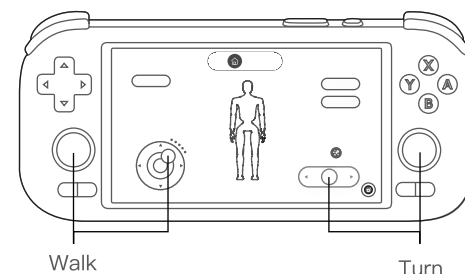
1 Dance

1. The robot should be in motion-ready posture, standing on a flat surface with adequate friction
2. Leave sufficient safety clearance around the robot
3. Start dancing!



2 Walk

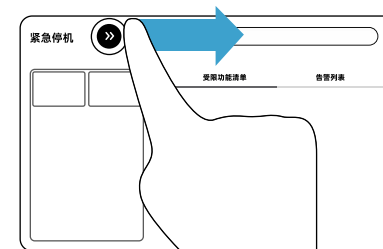
1. The robot should be in motion-ready posture, standing on a flat surface with adequate friction
2. Move the on-screen joystick on the home page to control the robot's direction.
3. Start walking!



Emergency Stop 04

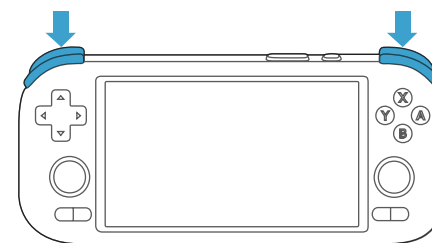
When the robot encounters risks such as collision or tipping over, trigger an emergency stop immediately

In any state, you can access "Emergency Shutdown" via the floating window on the client app

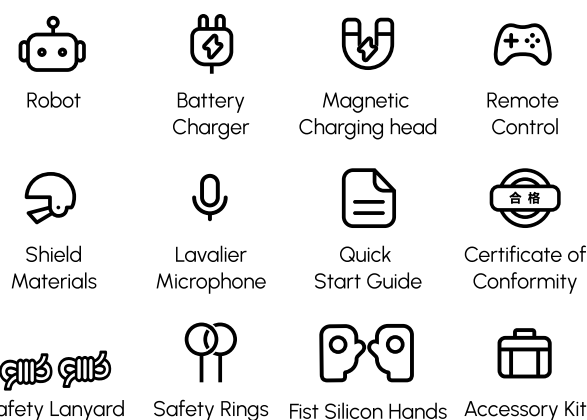


After sliding the emergency stop button, the robot will immediately cease all motion-please operate with caution

Alternatively, long press all four buttons on the top simultaneously to trigger an immediate emergency stop



Package Contents 05



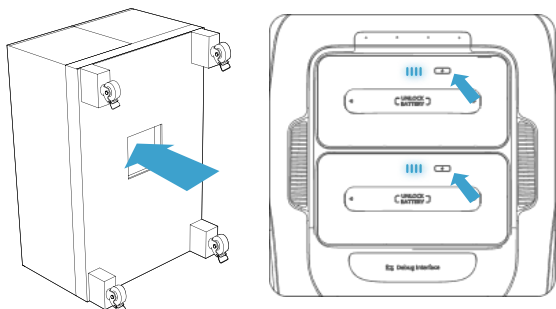


首次开箱 01

1 电池激活

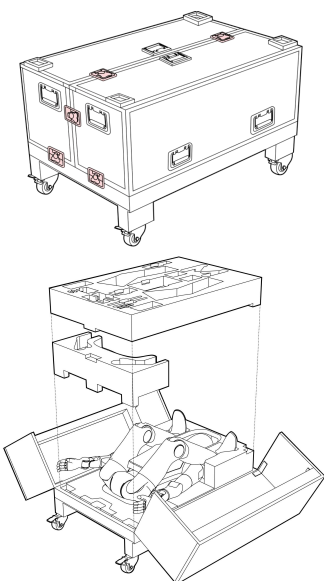
首次开箱，或电池包处于储运模式时，需完成激活：

1. 包装箱竖直放置，打开底部开窗
2. 短按+长按1s 电池包电源键，指示灯全亮即为激活成功
3. 对第二块电池重复上述操作，确保两块电池均已激活



2 平躺放置包装箱&开箱

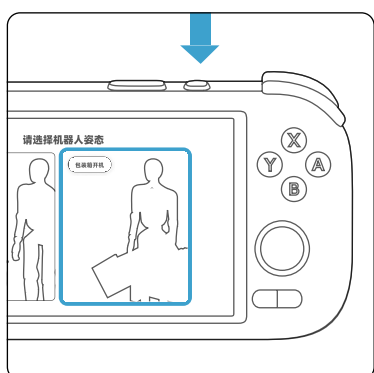
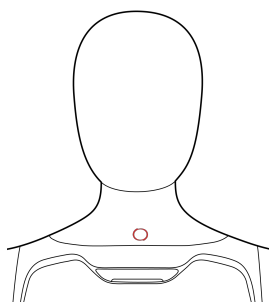
打开包装箱上盖 移除两块泡绵



3 首次从包装箱中自动站起

⚠ 自动站起时请勿触碰，并在箱周预留充足的安全空间

1. 长按胸前整机电源键开机
2. 长按顶部开机键3s，打开遥控器
3. 选择「包装箱开机」，机器人按指引出箱



- 腿部由折叠自动转为平躺
- 回收腿部，借助手臂支撑完成站立

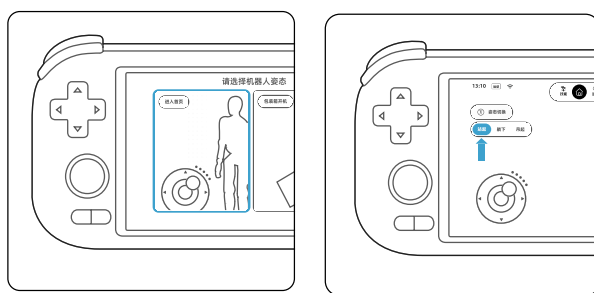
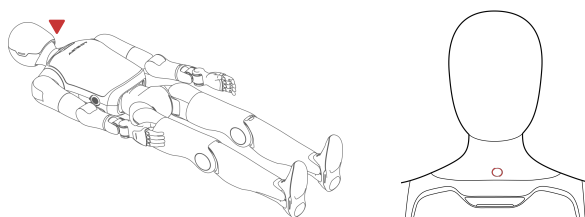
日常开关 02

1 日常开机

日常使用无需重复开箱流程，直接开机：

⚠ 请在机器人周围预留充足的安全空间，避免机器人发生碰撞

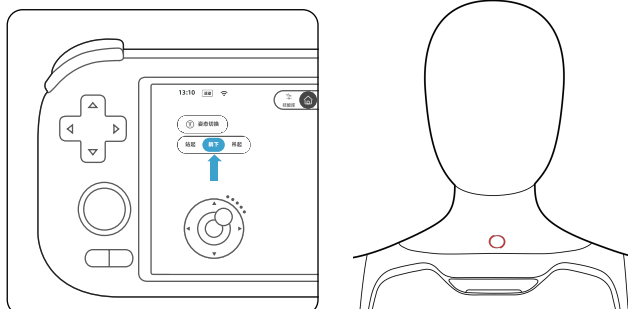
1. 机器人平躺放置于地面
2. 长按胸前整机电源键3s后开机
3. 遥控器连接机器人，进入首页，执行站起动作
4. 执行姿态切换：躺下→站起，等待机器人自动完成



2 平躺关机流程

⚠ 请确保机器人周围3m半径的安全空间，避免碰撞

1. 遥控器连接机器人
2. 遥控机器人躺下
3. 短按胸前开关键，按语音提示操作关机

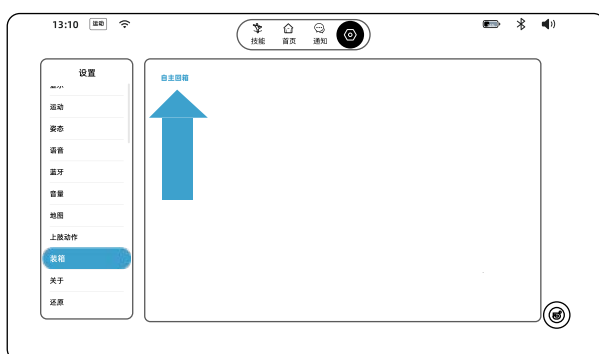


3 收纳装箱

⚠ 确保机身周围 3m 半径安全空间，防止摔倒

机器人稳定站立时,可按以下步骤安全装箱:

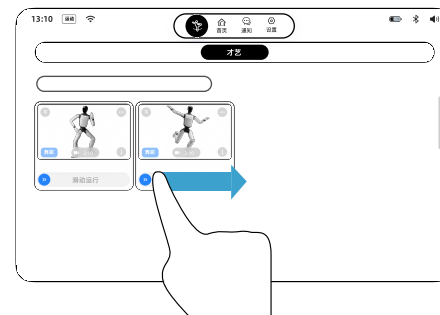
1. 打开遥控器「设置」→「装箱」→「自主回箱」
2. 按照遥控器提示，开始自动进箱



基础操作 03

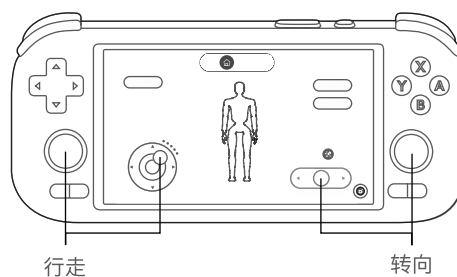
1 舞蹈

1. 机器人在运动姿态下，站立在平整且有一定摩擦力的地面
2. 留出一定的安全空间
3. 开始舞蹈！



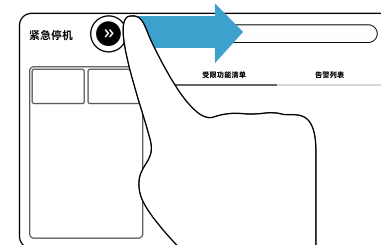
2 行走

1. 机器人在运动姿态下，站立在平整且有一定摩擦力的地面
2. 在客户端首页推动摇杆，可控制机器人方向
3. 开始走吧！

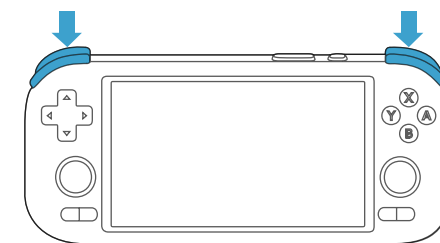


紧急停机 04

当机器人出现碰撞、倾倒等风险时，请立即急停
在任何状态下，均可通过客户端悬浮球 进入「紧急停机」



滑动急停按钮后，机器人会立即停止动作，请谨慎操作
或同时长按顶部四个按键，即可立即急停



包装清单 05



整机



电池充电器



磁吸充电头



遥控器



防护材料



领夹麦克风



快速入门手册



出厂合格证



安全吊绳



配件包



握拳硅胶手



安全吊环